

ISSN 2077–9879

Eurasian Mathematical Journal

2015, Volume 6, Number 4

Founded in 2010 by
the L.N. Gumilyov Eurasian National University
in cooperation with
the M.V. Lomonosov Moscow State University
the Peoples' Friendship University of Russia
the University of Padua

Supported by the ISAAC
(International Society for Analysis, its Applications and Computation)
and
by the Kazakhstan Mathematical Society

Published by
the L.N. Gumilyov Eurasian National University
Astana, Kazakhstan

EURASIAN MATHEMATICAL JOURNAL

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KORDAN NAURYZKHANOVICH OSPANOV

(to the 60th birthday)



On 25 September 2015 Kordan Nauryzhanovich Ospanov, professor of the Department "Fundamental Mathematics" of the L.N. Gumilyov Eurasian National University, Doctor of Physical and Mathematical Sciences (2000), a member of the Editorial Board of our journal, celebrated his 60th birthday.

He was born on September 25, 1955, in the village Zhanatalap of the Zhanaarka district of the Karaganda region. In 1976 he graduated from the Kazakh State University, and in 1981 he completed his postgraduate studies at the Abay Kazakh Pedagogical Institute.

Scientific works of K.N. Ospanov are devoted to application of methods of functional analysis to the theory of differential equations. On the basis of a local approach to the resolvent representation he has found weak conditions for the solvability of the singular generalized Cauchy-Riemann system and established coercive estimates for its solution. He has obtained a criterion of the spectrum discreteness for the resolvent of the system and the exact in order estimates of singular values and Kolmogorov widths. He has original research results on the coercive solvability of the quasilinear singular generalized Cauchy-Riemann system and degenerate Beltrami-type system. He has established important smoothness and approximation properties of non strongly elliptic systems. K.N. Ospanov has found separability conditions in Banach spaces for singular linear and quasi-linear second-order differential operators with growing intermediate coefficients and established a criterion for the compactness of its resolvent and finiteness of the resolvent type.

His results have contributed to a significant development of the theory of two-dimensional singular elliptic systems, degenerate differential equations and non strongly elliptic boundary value problems.

K.N. Ospanov has published more than 140 scientific papers. The list of his most important publications one may see on the

<http://mmf.enu.kz/images/stories/photo/pasport/fm/ospanov>

K.N. Ospanov is an Honoured Worker of Education of the Republic of Kazakhstan, and he was awarded the state grant "The best university teacher".

The Editorial Board of the Eurasian Mathematical Journal is happy to congratulate Kordan Nauryzhanovich Ospanov on occasion of his 60th birthday, wishes him good health and further productive work in mathematics and mathematical education.

ON CONDITIONS OF THE SOLVABILITY OF NONLOCAL MULTI-POINT BOUNDARY VALUE PROBLEMS FOR QUASI-LINEAR SYSTEMS OF HYPERBOLIC EQUATIONS

A.T. Assanova, A.E. Imanchiev

Communicated by K.N. Ospanov

Key words: nonlocal problem, multi-point condition, quasi-linear hyperbolic equation, solvability.

AMS Mathematics Subject Classification: 35L20, 35L55, 34B08, 35L72.

Abstract. A nonlocal multi-point boundary value problem for a system of quasi-linear hyperbolic equations is investigated. Based on the results for linear problems coefficient conditions are established ensuring the existence of classical solutions to nonlocal multi-point boundary value problem for a system of quasi-linear hyperbolic equations, and algorithms of finding these solutions are suggested.

1 Introduction

We consider the following nonlocal multi-point boundary value problem on $\bar{\Omega} = [0, T] \times [0, \omega]$ for a second-order system of quasilinear hyperbolic equations

$$\frac{\partial^2 u}{\partial t \partial x} = A(t, x) \frac{\partial u}{\partial x} + f\left(t, x, u, \frac{\partial u}{\partial t}\right), \quad u \in R^n, \quad (1.1)$$

$$\sum_{i=0}^m \left\{ P_i(x) \frac{\partial u(t_i, x)}{\partial x} + S_i(x) \frac{\partial u(t_i, x)}{\partial t} + U_i(x) u(t_i, x) \right\} = \varphi(x), \quad x \in [0, \omega], \quad (1.2)$$

$$u(t, 0) = \psi(t), \quad t \in [0, T], \quad (1.3)$$

where $u(t, x) = \text{col}(u_1(t, x), u_2(t, x), \dots, u_n(t, x))$ is the unknown function, the $n \times n$ matrices $A(t, x)$, $P_i(x)$, $S_i(x)$, $U_i(x)$, $i = \overline{0, m}$, and the n -vector function $f(t, x, u, \frac{\partial u}{\partial t})$ are continuous on $\bar{\Omega} \times R^n \times R^n$, the n -vector function φ is continuous on $[0, \omega]$, and the n -vector function ψ is continuously differentiable on $[0, T]$, $0 = t_0 < t_1 < \dots < t_{m-1} < t_m = T$.

The study of nonlocal boundary value problems for hyperbolic-type equations was initiated in the 1960s (see [12, 17, 19, 20, 22] and references therein). Sufficient conditions for the existence and uniqueness of solutions to such problems have been obtained by various methods. In the last several decades nonlocal multi-point problems for hyperbolic equations appeared to be of great interest to specialists [11, 18, 20, 24]. Motivated by this, in [9, 10] the linear problem corresponding to (1.1)–(1.3) has

been investigated. Necessary and sufficient conditions for the well-posedness of linear problem were found in terms of the initial data. The main results of [9] were based on the equivalence of the well-posedness of nonlocal multi-point boundary value problem for a system of hyperbolic equations and a family of multi-point boundary value problems for the systems of ordinary differential equations. Using the parametrization method [14] necessary and sufficient conditions of the unique solvability of a family of multi-point boundary value problems for a system of ordinary differential equations are established in terms of the initial data. The coefficient criteria of unique solvability of the corresponding linear nonlocal multi-point boundary value problem (1.1)–(1.3) are obtained.

In [2,3] a nonlocal boundary value problem with data on the characteristics of the corresponding system of hyperbolic equations is considered for $t_0 = 0$, $t_1 = T$. Sufficient conditions are given for the existence and uniqueness of a classical solution to problem (1.1)–(1.3), when $m = 1$, in terms of the initial data. In [4-6, 8, 13] this problem, by introducing new functions, was reduced to a family of the two-point boundary value problems for ordinary differential equations and functional relations. Coefficient criteria of well-posedness of the considered problem were obtained. Problem (1.1)–(1.3), when $m = 1$, is investigated by this method in [7].

In this paper, we establish sufficient coefficient conditions of the unique solvability of problem (1.1)–(1.3) by introducing some additional functions and applying related results for families of multi-point boundary value problems for systems of ordinary differential equations; we suggest an algorithm for finding a solution.

Let $C(\bar{\Omega}, R^n)$ be the space of all continuous functions $u : \bar{\Omega} \rightarrow R^n$ on $\bar{\Omega}$ with the norm

$$\|u\|_0 = \max_{(t,x) \in \bar{\Omega}} \|u(t, x)\|,$$

and $C^{1,1}(\bar{\Omega}, R^n)$ be the space of all continuous functions $u : \bar{\Omega} \rightarrow R^n$ on $\bar{\Omega}$ continuously differentiable with respect to t and x with the norm $\|u\|_1 = \max\left(\|u\|_0, \left\|\frac{\partial u}{\partial x}\right\|_0, \left\|\frac{\partial u}{\partial t}\right\|_0\right)$.

A function $u(t, x) \in C(\bar{\Omega}, R^n)$, that has partial derivatives $\frac{\partial u(t, x)}{\partial x} \in C(\bar{\Omega}, R^n)$, $\frac{\partial u(t, x)}{\partial t} \in C(\bar{\Omega}, R^n)$, $\frac{\partial^2 u(t, x)}{\partial t \partial x} \in C(\bar{\Omega}, R^n)$ is called a classical solution to problem (1.1)–(1.3) if it satisfies system (1.1) for all $(t, x) \in \bar{\Omega}$ and meets boundary conditions (1.2) and (1.3).

2 Family of multi-point boundary value problem for systems of ordinary differential equations. Main result

We introduce new unknown functions $v(t, x) = \frac{\partial u(t, x)}{\partial x}$ and $w(t, x) = \frac{\partial u(t, x)}{\partial t}$ and reduce problem (1.1)–(1.3) to the equivalent problem

$$\frac{\partial v}{\partial t} = A(t, x)v + f(t, x, u, w), \quad (t, x) \in \bar{\Omega}, \quad (2.1)$$

$$\sum_{i=0}^m P_i(x)v(t_i, x) = \varphi(x) - \sum_{i=0}^m \left\{ S_i(x)w(t_i, x) + U_i(x)u(t_i, x) \right\}, \quad x \in [0, \omega], \quad (2.2)$$

$$u(t, x) = \psi(t) + \int_0^x v(t, \xi) d\xi, \quad w(t, x) = \dot{\psi}(t) + \int_0^x \frac{\partial v(t, \xi)}{\partial t} d\xi, \quad (2.3)$$

where $(t, x) \in \bar{\Omega}$.

A triple $\{v(t, x), u(t, x), w(t, x)\}$ of continuous on $\bar{\Omega}$ functions is called a solution to problem (2.1)–(2.3) if the function $v(t, x) \in C(\bar{\Omega}, R^n)$ has a continuous derivative with respect to t on $\bar{\Omega}$ and satisfies the one-parametered family of multi-point boundary value problems for the system of ordinary differential equations (2.1), (2.2), where the functions $u(t, x)$ and $w(t, x)$ are connected to $v(t, x)$ and $\frac{\partial v(t, x)}{\partial t}$ according to the functional relations (2.3).

Let $u^*(t, x)$ be a classical solution to problem (1.1)–(1.3). Then the triple $\{v^*(t, x), u^*(t, x), w^*(t, x)\}$, where $v^*(t, x) = \frac{\partial u^*(t, x)}{\partial x}$, $w^*(t, x) = \frac{\partial u^*(t, x)}{\partial t}$, becomes a solution to problem (2.1)–(2.3). Conversely, if a triple $\{\tilde{v}(t, x), \tilde{u}(t, x), \tilde{w}(t, x)\}$ is a solution to problem (2.1)–(2.3), then $\tilde{u}(t, x)$ becomes a classical solution to problem (1.1)–(1.3).

For fixed $w(t, x)$, $u(t, x)$ in problem (2.1)–(2.3) it is necessary to find a solution to a one-parametered family of multi-point boundary value problems for system of ordinary differential equations.

Consider the family of multi-point boundary value problems for the system of ordinary differential equations

$$\frac{\partial v}{\partial t} = A(t, x)v + F(t, x), \quad t \in [0, T], \quad x \in [0, \omega], \quad v \in R^n, \quad (2.4)$$

$$\sum_{i=0}^m P_i(x)v(t_i, x) = \Phi(x), \quad x \in [0, \omega], \quad (2.5)$$

where $F(t, x) \in C(\bar{\Omega}, R^n)$ and $\Phi(x) \in C([0, \omega], R^n)$.

Continuous function $v : \bar{\Omega} \rightarrow R^n$ which has a continuous derivative with respect to t on Ω is called a solution to the family of multi-point boundary value problems (2.4)–(2.5) if it satisfies system (2.4) and condition (2.5) for all $(t, x) \in \bar{\Omega}$ and $x \in [0, \omega]$, respectively.

For fixed $x \in [0, \omega]$ problem (2.4)–(2.5) is a linear multi-point boundary value problem for the system of ordinary differential equations. The different types of multi-point boundary value problems for differential equations have been investigated by various methods [1, 15, 16, 21, 23]. Suppose a variable x is changed on $[0, \omega]$; then we obtain a family of multi-point boundary value problems for ordinary differential equations.

Definition 1. A family of multi-point boundary value problems (2.4)–(2.5) is called well-posed solvable with a constant K if for arbitrary $F(t, x) \in C(\bar{\Omega}, R^n)$ and $\Phi(x) \in C([0, \omega], R^n)$ it has a unique solution $v(t, x) \in C(\bar{\Omega}, R^n)$ and for this solution the following estimate holds

$$\max_{t \in [0, T]} \|v(t, x)\| \leq K \max \left(\max_{t \in [0, T]} \|F(t, x)\|, \|\Phi(x)\| \right),$$

where the constant K is independent of $F(t, x)$, $\Phi(x)$ and $x \in [0, \omega]$.

Consider the sets

$$\begin{aligned} G(\psi, \dot{\psi}, \rho) &= \{(t, x, u, w) : (t, x) \in \bar{\Omega}, \|u - \psi(t)\| < \rho, \|w - \dot{\psi}(t)\| < \rho\}, \\ S(\psi(t), \rho) &= \{u \in C^{1,1}(\bar{\Omega}, R^n) : \|u - \psi\|_1 < \rho\}. \end{aligned}$$

Condition Lip. Function $f(t, x, u, w)$ is continuous in $(t, x) \in \bar{\Omega}$ for fixed u and w and satisfies the Lipschitz condition with respect to u and w on the set $G(\psi, \dot{\psi}, \rho)$, i.e.

$$\|f(t, x, u, w) - f(t, x, \bar{u}, \bar{w})\| \leq l_1(t, x)\|u - \bar{u}\| + l_2(t, x)\|w - \bar{w}\|,$$

where $l_i(t, x) \geq 0$ are functions continuous on $\bar{\Omega}$ for $i = 1, 2$.

We set $F^0(t, x) = f(t, x, \psi(t), \dot{\psi}(t))$, $\Phi^0(x) = \varphi(x) - \sum_{i=0}^m \left\{ S_i(x) \dot{\psi}(t_i) + U_i(x) \psi(t_i) \right\}$,

$$\tilde{L}(x) = \sum_{i=0}^m \left\{ \|S_i(x)\| + \|U_i(x)\| \right\},$$

$$l_0(x) = \max \left\{ \max_{t \in [0, T]} l_1(t, x) + \max_{t \in [0, T]} l_2(t, x), \tilde{L}(x) \right\}, \quad \alpha(x) = \max_{t \in [0, T]} \|A(t, x)\|,$$

$$\rho_1(x) = \max(K, \alpha(x)K + 1)l_0(x),$$

$$\rho_2(x) = \max(K, \alpha(x)K + 1) \max \left\{ \max_{t \in [0, T]} \|F^0(t, x)\|, \|\Phi^0(x)\| \right\},$$

$$\text{and } \rho_3(x) = \rho_2(x) \exp \left\{ x \max_{x \in [0, \omega]} \rho_1(x) \right\}.$$

To find conditions for the existence of a unique classical solution to problem (1.1)–(1.3), we consider the equivalent problem (2.1)–(2.3) and suggest an algorithm for solving it.

Step 0. Solving the family of multi-point boundary value problems (2.1)–(2.2) for $u(t, x) = \psi(t)$ and $w(t, x) = \dot{\psi}(t)$, we obtain $v^{(0)}(t, x)$ for $(t, x) \in \bar{\Omega}$. Functional relations (2.3) with $v(t, x) = v^{(0)}(t, x)$ and $\frac{\partial v(t, x)}{\partial x} = \frac{\partial v^{(0)}(t, x)}{\partial x}$ determine $u^{(0)}(t, x)$ and $w^{(0)}(t, x)$ for $(t, x) \in \bar{\Omega}$.

Step 1. Solving the family of multi-point boundary value problems (2.1)–(2.2) for $u(t, x) = u^{(0)}(t, x)$ and $w(t, x) = w^{(0)}(t, x)$, we obtain $v^{(1)}(t, x)$ for $(t, x) \in \bar{\Omega}$. Functional relations (2.3) with $v(t, x) = v^{(1)}(t, x)$ and $\frac{\partial v(t, x)}{\partial x} = \frac{\partial v^{(1)}(t, x)}{\partial x}$ determine $u^{(1)}(t, x)$ and $w^{(1)}(t, x)$ for $(t, x) \in \bar{\Omega}$.

Continuing in this way, we obtain $v^{(k)}(t, x)$, $u^{(k)}(t, x)$ and $w^{(k)}(t, x)$ for $(t, x) \in \bar{\Omega}$ at the k th step, where $k = 0, 1, 2, \dots$

Sufficient conditions for the implementation and convergence of the algorithm and the existence of a unique classical solution to problem (1.1)–(1.3) are ensured by the following theorem.

Theorem 2.1. *Suppose that*

- (i) $f(t, x, u, w)$ is a function satisfying Condition Lip;
- (ii) the family of multi-point boundary value problems (2.4), (2.5) is well-posed solvable with the constant K ;

$$(iii) \text{ for some } \rho > 0 \int_0^x \rho_3(\xi) d\xi \leq \rho \text{ for all } x \in [0, \omega].$$

Then, problem (1.1)–(1.3) has a unique classical solution $u^*(t, x)$ belonging to $S(\psi(t), \rho)$.

Proof. Consider problem (2.1)–(2.3) which is equivalent to problem (1.1)–(1.3). Using the method of successive approximations, we find a solution $v(t, x)$. For the initial approximation of $u(t, x)$ and $w(t, x)$ we take $\psi(t)$, $\dot{\psi}(t)$ respectively, and then find $v^{(0)}(t, x)$ from the problem

$$\frac{\partial v}{\partial t} = A(t, x)v + F^0(t, x), \quad (2.6)$$

$$\sum_{i=0}^m P_i(x)v(t_i, x) = \Phi^0(x), \quad x \in [0, \omega]. \quad (2.7)$$

Problem (2.6)–(2.7) is a family of multi-point boundary value problems for a system of ordinary differential equations. This problem is investigated in [9] by the parametrization method [14]. Necessary and sufficient conditions of unique and well-posed solvability of the family of boundary value problems (2.4)–(2.5) were established in terms of initial data. An estimate of the solution to investigated problem in terms of the initial data was also obtained.

By assumption (ii) of the theorem, problem (2.6)–(2.7) is well-posed solvable. Therefore, problem (2.6)–(2.7) has a unique solution $v^{(0)}(t, x)$ and the following estimates hold

$$\begin{aligned} \max_{t \in [0, T]} \|v^{(0)}(t, x)\| &\leq K \max(\max_{t \in [0, T]} \|F^0(t, x)\|, \|\Phi^0(x)\|), \\ \max_{t \in [0, T]} \left\| \frac{\partial v^{(0)}(t, x)}{\partial t} \right\| &\leq [\alpha(x)K + 1] \max(\max_{t \in [0, T]} \|F^0(t, x)\|, \|\Phi^0(x)\|). \end{aligned}$$

Using relations (2.3) we find $u^{(0)}(t, x)$ and $w^{(0)}(t, x)$:

$$u^{(0)}(t, x) = \psi(t) + \int_0^x v^{(0)}(t, \xi) d\xi, \quad w^{(0)}(t, x) = \dot{\psi}(t) + \int_0^x \frac{\partial v^{(0)}(t, \xi)}{\partial t} d\xi.$$

The following estimates are satisfied:

$$\begin{aligned} \max_{t \in [0, T]} \|u^{(0)}(t, x) - \psi(t)\| &\leq \int_0^x \max_{t \in [0, T]} \|v^{(0)}(t, \xi)\| d\xi, \\ \max_{t \in [0, T]} \|w^{(0)}(t, x) - \dot{\psi}(t)\| &\leq \int_0^x \max_{t \in [0, T]} \left\| \frac{\partial v^{(0)}(t, \xi)}{\partial t} \right\| d\xi. \end{aligned}$$

Then, we have

$$\begin{aligned} &\max(\max_{t \in [0, T]} \|u^{(0)}(t, x) - \psi(t)\|, \max_{t \in [0, T]} \|w^{(0)}(t, x) - \dot{\psi}(t)\|) \\ &\leq \int_0^x \max \left(\max_{t \in [0, T]} \|v^{(0)}(t, \xi)\|, \max_{t \in [0, T]} \left\| \frac{\partial v^{(0)}(t, \xi)}{\partial t} \right\| \right) d\xi \end{aligned}$$

$$\leq \int_0^x \max(K, \alpha(\xi)K + 1) \max(\max_{t \in [0, T]} \|F^0(t, \xi)\|, \|\Phi^0(\xi)\|) d\xi = \int_0^x \rho_2(\xi) d\xi.$$

Suppose $u^{(k-1)}(t, x)$ and $w^{(k-1)}(t, x)$ are known. Then $v^{(k)}(t, x)$ can be found from the problem (2.1)–(2.2), where $w(t, x) = w^{(k-1)}(t, x)$, $u(t, x) = u^{(k-1)}(t, x)$, $m = 1, 2, \dots$, namely

$$\frac{\partial v^{(k)}}{\partial t} = A(t, x)v^{(k)} + f(t, x, u^{(k-1)}(t, x), w^{(k-1)}(t, x)), \quad (2.8)$$

$$\sum_{i=0}^m P_i(x)v^{(k)}(t_i, x) = \varphi(x) - \sum_{i=0}^m \left\{ S_i(x)w^{(k-1)}(t_i, x) + U_i(x)u^{(k-1)}(t_i, x) \right\}, \quad (2.9)$$

where $x \in [0, \omega]$.

By assumption (ii) of the theorem, problem (2.8)–(2.9) is well-posed solvable. Therefore, problem (2.8)–(2.9) has a unique solution $v^{(0)}(t, x)$ and there hold the estimates

$$\begin{aligned} \max_{t \in [0, T]} \|v^{(k)}(t, x)\| &\leq K \max(\max_{t \in [0, T]} \|F^{(k-1)}(t, x)\|, \|\Phi^{(k-1)}(x)\|), \\ \max_{t \in [0, T]} \left\| \frac{\partial v^{(k)}(t, x)}{\partial t} \right\| &\leq [\alpha(x)K + 1] \max(\max_{t \in [0, T]} \|F^{(k-1)}(t, x)\|, \|\Phi^{(k-1)}(x)\|), \end{aligned}$$

where

$$\begin{aligned} F^{(k-1)}(t, x) &= f(t, x, u^{(k-1)}(t, x), w^{(k-1)}(t, x)), \\ \Phi^{(k-1)}(x) &= \varphi(x) - \sum_{i=0}^m \left\{ S_i(x)w^{(k-1)}(t_i, x) + U_i(x)u^{(k-1)}(t_i, x) \right\}. \end{aligned}$$

Once $v^{(k)}(t, x)$ is found, the successive approximations for $u(t, x)$ and $w(t, x)$ are found from relations (2.3):

$$u^{(k)}(t, x) = \psi(t) + \int_0^x v^{(k)}(t, \xi) d\xi, \quad w^{(k)}(t, x) = \dot{\psi}(t) + \int_0^x \frac{\partial v^{(k)}(t, \xi)}{\partial t} d\xi. \quad (2.10)$$

The functions $u^{(k)}(t, x)$ and $w^{(k)}(t, x)$ satisfy the following inequalities

$$\begin{aligned} \max_{t \in [0, T]} \|u^{(k)}(t, x) - \psi(t)\| &\leq \int_0^x \max_{t \in [0, T]} \|v^{(k)}(t, \xi)\| d\xi, \\ \max_{t \in [0, T]} \|w^{(k)}(t, x) - \dot{\psi}(t)\| &\leq \int_0^x \max_{t \in [0, T]} \left\| \frac{\partial v^{(k)}(t, \xi)}{\partial t} \right\| d\xi. \end{aligned}$$

Then, we get

$$\begin{aligned} &\max \left(\max_{t \in [0, T]} \|u^{(k)}(t, x) - \psi(t)\|, \max_{t \in [0, T]} \|w^{(k)}(t, x) - \dot{\psi}(t)\| \right) \\ &\leq \int_0^x \max \left(\max_{t \in [0, T]} \|v^{(k)}(t, \xi)\|, \max_{t \in [0, T]} \left\| \frac{\partial v^{(k)}(t, \xi)}{\partial t} \right\| \right) d\xi \\ &\leq \int_0^x \max [K, \alpha(\xi)K + 1] \max \left(\max_{t \in [0, T]} \|F^{(k-1)}(t, \xi)\|, \|\Phi^{(k-1)}(\xi)\| \right) d\xi \end{aligned}$$

$$\leq \int_0^x \rho_3(\xi) d\xi,$$

i.e. $u^{(k)} \in S(\psi(t), \rho)$.

We consider the differences

$$\Delta v^{(k)}(t, x) = v^{(k+1)}(t, x) - v^{(k)}(t, x),$$

$$\Delta u^{(k)}(t, x) = u^{(k+1)}(t, x) - u^{(k)}(t, x),$$

$$\Delta w^{(k)}(t, x) = w^{(k+1)}(t, x) - w^{(k)}(t, x),$$

and using the well-posedness of problem (2.4)–(2.5) we establish the following estimates

$$\max_{t \in [0, T]} \|\Delta v^{(k)}(t, x)\| \leq K l_0(x) \max \left(\max_{t \in [0, T]} \|\Delta u^{(k-1)}(t, x)\|, \max_{t \in [0, T]} \|\Delta w^{(k-1)}(t, x)\| \right), \quad (2.11)$$

$$\begin{aligned} & \max_{t \in [0, T]} \left\| \frac{\partial \Delta v^{(k)}(t, x)}{\partial t} \right\| \leq \\ & \leq \left(\alpha(x) K + 1 \right) l_0(x) \max \left(\max_{t \in [0, T]} \|\Delta u^{(k-1)}(t, x)\|, \max_{t \in [0, T]} \|\Delta w^{(k-1)}(t, x)\| \right), \end{aligned} \quad (2.12)$$

$$\max_{t \in [0, T]} \|\Delta u^{(k)}(t, x)\| \leq \int_0^x \max_{t \in [0, T]} \|\Delta v^{(k)}(t, \xi)\| d\xi,$$

$$\max_{t \in [0, T]} \|\Delta w^{(k)}(t, x)\| \leq \int_0^x \max_{t \in [0, T]} \left\| \frac{\partial \Delta v^{(k)}(t, \xi)}{\partial t} \right\| d\xi.$$

This implies the main inequality

$$\begin{aligned} & \max \left(\max_{t \in [0, T]} \|\Delta u^{(k)}(t, x)\|, \max_{t \in [0, T]} \|\Delta w^{(k)}(t, x)\| \right) \\ & \leq \int_0^x \rho_1(\xi) \max \left(\max_{t \in [0, T]} \|\Delta u^{(k-1)}(t, \xi)\|, \max_{t \in [0, T]} \|\Delta w^{(k-1)}(t, \xi)\| \right) d\xi. \end{aligned} \quad (2.13)$$

As inequality (2.13) is fair for $k = 1, 2, \dots$, then consistently substituting the corresponding differences in the right-hand side, we will get

$$\begin{aligned} & \max \left(\max_{t \in [0, T]} \|\Delta u^{(k)}(t, x)\|, \max_{t \in [0, T]} \|\Delta w^{(k)}(t, x)\| \right) \\ & \leq \frac{1}{(k-1)!} \int_0^x [\xi \max_{\xi_1 \in [0, \omega]} \rho_1(\xi_1)]^{k-1} \rho_2(\xi) d\xi. \end{aligned}$$

Hereof, we get that at $k \rightarrow \infty$ the sequences $u^{(k)}(t, x)$, $w^{(k)}(t, x)$ converge uniformly to $u^*(t, x)$, $w^*(t, x)$ on $\bar{\Omega}$. Then from relations (2.11)–(2.12) it follows that sequences $v^{(k)}(t, x)$, $\frac{\partial v^{(k)}(t, x)}{\partial t}$ also converge uniformly on $\bar{\Omega}$ to $v^*(t, x)$, $\frac{\partial v^*(t, x)}{\partial t}$, respectively.

This means that the triple of functions $\{v^*(t, x), u^*(t, x), w^*(t, x)\}$ is a solution to problem (2.1)–(2.3) and the following inequalities hold

$$\max \left(\max_{t \in [0, T]} \|u^*(t, x) - \psi(t)\|, \max_{t \in [0, T]} \|w^*(t, x) - \dot{\psi}(t)\| \right) \leq \int_0^\omega \rho_3(\xi) d\xi \leq \rho,$$

$$\max\left(\max_{t \in [0, T]} \|v^*(t, x)\|, \max_{t \in [0, T]} \left\| \frac{\partial v^*(t, x)}{\partial t} \right\| \right) \leq \int_0^\omega \rho_3(\xi) d\xi \leq \rho,$$

i.e. $u^* \in S(\psi(t), \rho)$.

As problems (2.1)–(2.3) and (1.1)–(1.3) are equivalent, the function $u^*(t, x)$ belonging to $S(\psi(t), \rho)$, will be a classical solution to problem (1.1)–(1.3). The uniqueness of the solution is proved by the contradiction method. \square

Acknowledgments

This work supported by Grant No. 0822/ $\Gamma\Phi$ 4 (2015-2017) of the Science Committee of the Ministry of education and Science of the Republic of Kazakhstan.

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Received: 18.06.2015