

INVERSE EXTREMAL PROBLEM
FOR VARIATIONAL FUNCTIONALS

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Abstract. We investigate an inverse extremal problem for the variational functionals: to describe, under certain conditions, all types of variational functionals having a local extremum (in case of the space $C^1[a; b]$) or a compact extremum (in case of the Sobolev space $W^{1,2}[a; b] = H^1[a; b]$) at a given point of the corresponding function space. The non-locality conditions for a compact extrema of variational functionals are described as well.

1 Introduction. Preliminaries

The classical scheme of proving the existence of a local extremum for the one-dimensional Euler-Lagrange variational functional

$$\Phi(y) = \int_a^b f(x, y, y') dx \mapsto \text{extr} \quad (y \in C^1[a; b])$$

at an extremal point y assumes [5], [4] checking the strengthened Legendre condition $f_{y'y'}(x, y, y') \neq 0$ and the Jacobi condition $U(x) \neq 0$ ($a < x \leq b$) for the Hamilton–Jacobi equation:

$$-\frac{d}{dx} \left[f_{y'y'}(x, y, y') U' \right] + \left[-\frac{d}{dx} (f_{yy'}(x, y, y')) + f_{y^2}(x, y, y') \right] U = 0$$

$$(U(a) = 0, U'(a) = 1).$$

The second step is the most laborious, it requires to solve a rather complicated equation in order to get, in fact, a very small information about the behaviour of the solution U .

Moreover, the initial conditions $U(a) = 0, U'(a) = 1$, have as a consequence automatic fulfilment of the Jacobi condition near a . The only question is – how long is the appropriate interval?

In the recent author's paper [8], it was shown that the interval satisfying the Jacobi condition can be chosen depending only on the form of the integrand f and not depending on a concrete extremal. More precisely, the main result distinguishes two cases depending on the range of the coefficients in the Hamilton-Jacobi equation. In the first case, an extremum is guaranteed without any restriction on the length of $[a; b]$, in the second one, such a restriction is present. This result remains valid also for the case of a compact extremum in the Sobolev space $H^1[a; b]$.

Let us formulate these results considering first the classical C^1 -case.

Theorem 1. *Let the variational functional*

$$\Phi(y) = \int_a^b f(x, y, y') dx \quad (y \in C^1[a; b], y(a) = y(b) = 0, f \in C^2, f_{yz} \in C^1) \quad (1.1)$$

satisfy at a point $y_0(\cdot) \in C^2[a; b]$ the Euler-Lagrange equation

$$f_y(x, y_0, y'_0) - \frac{d}{dx} [f_z(x, y_0, y'_0)] = 0. \quad (1.2)$$

Denote

$$p := \min_{a \leq x \leq b} f_{z^2}(x, y_0(x), y'_0(x));$$

$$q := \min_{a \leq x \leq b} \left[f_{y^2}(x, y_0(x), y'_0(x)) - \frac{d}{dx} (f_{yz}(x, y_0(x), y'_0(x))) \right].$$

Then, under the boundary conditions $y(a) = y_0(a)$, $y(b) = y_0(b)$,

- 1) for $p > 0$, $q \geq 0$, $\Phi(y)$ attains a strong local minimum at $y_0(\cdot)$ (without any restriction on the length of $[a; b]$);*
- 2) for $p > 0$, $q < 0$, and under the restriction*

$$b - a < \frac{\pi}{4} \sqrt{\frac{p}{|q|}}, \quad (1.3)$$

on the length of $[a; b]$, $\Phi(y)$ attains a strong local minimum at $y_0(\cdot)$ as well.

An analogous result holds for a compact extrema of a variational functional in the Sobolev H^1 -case.

Theorem 2. *Let the variational functional*

$$\Phi(y) = \int_a^b f(x, y, y') dx \quad (y \in H^1[a; b], y(a) = y(b) = 0, f \in W_K^2(z)) \quad (1.4)$$

satisfy at a $W^{2,2}$ -smooth point $y_0(\cdot)$ the Euler-Lagrange equation. Then, under the conditions and notation of Theorem 1,

- 1) for $p > 0$, $q \geq 0$, $\Phi(y)$ attains a strong K -minimum at $y_0(\cdot)$ (without any restriction on the length of $[a; b]$);
- 2) for $p > 0$, $q < 0$, and under the restriction

$$b - a < \frac{\pi}{4} \sqrt{\frac{p}{|q|}}$$

on the a length of $[a; b]$, $\Phi(y)$ attains a strong K -minimum at $y_0(\cdot)$ as well.

(The Weierstrass class $W_K^2(z)$ will be defined below).

These results simplify essentially finding of both a local extremum in the C^1 -case and a K -extremum in the H^1 -case for the variational functionals of type (1.1), (1.4). This allows setting the inverse problem: *to describe a general form of a variational functional having extremum at a given point (under the Euler-Lagrange and Legendre conditions).*

The paper is devoted to solution of this problem. The first item contains a solution of the inverse problem in $C^1[a; b]$ (Theorems 3, 4 below). The second item contains a solution of the inverse problem in $H^1[a; b]$ (Theorems 7 – 9 below).

The third item is auxiliary for the further investigation of K -extrema. It contains a description of integrands in the Weierstrass class $W^2K_2(z)$, which provides the appropriate analytical properties of variational functionals in H^1 (Theorem 10). The fourth item contains the so-called “stationary form of the Legendre-Jacobi conditions” (SLG) guaranteeing the existence of a K -extremum under a weaker restriction on the length of $[a; b]$. On the basis of that results, the fifth item contains a solution of the inverse problem in $H^1[a; b]$ under the (SLJ)-condition and the exponential (SLJ)-condition.

Next, the sixth item of the work consider the main properties of the mappings from the Weierstrass class $W_K^2(z)$ that allow to construct easily the extensive classes of the integrands from the Weierstrass class $W^2K_2(z)$. The final, seventh item of the work contains a description of an extensive enough class of the variational functionals having non-local compact extrema in $H^1[a, b]$.

2 Inverse extremal problem for variational functionals in $C^1[a; b]$

Let us set up the following problem: to find a general form of the variational functional (1.1) possessing local minimum at zero under the strengthened Legendre condition.

- 1) We shall write integrands f of functional (1.1) the form

$$f(x, y, z) = P(x, y) + Q(x, y) \cdot z + \frac{1}{2}R(x, y, z) \cdot z^2. \quad (2.1)$$

Then

$$P(x, y) = f(x, y, 0), \quad Q(x, y) = f_z(x, y, 0), \quad R(x, y, 0) = f_{z^2}(x, y, 0).$$

Under this notation, the Euler–Lagrange equation at the zero extremal takes the form

$$(Q_x - P_y)(x, 0) = 0 \quad (a \leq x \leq b); \quad (2.2)$$

and the strengthened Legendre condition at the zero extremal takes the form

$$R(x, 0, 0) =: p(x) > 0 \quad (a \leq x \leq b). \quad (2.3)$$

2) Choose an arbitrary function $P \in C^2$. Then a general form of Q follows by (2.2):

$$\begin{aligned} \left(Q_x(x, 0) = P_y(x, 0) \right) &\Rightarrow \left(Q(x, 0) = C + \int_a^x P_y(t, 0) dt \right) \Rightarrow \\ &\Rightarrow \left(Q(x, y) = C + \int_a^x P_y(t, 0) dt + \tilde{Q}(x, y), \text{ where } \tilde{Q}(x, 0) = 0 \right) \Rightarrow \\ &\Rightarrow \left(Q(x, y) = C + \int_a^x P_y(t, 0) dt + [q(x, y) - q(x, 0)] \right). \end{aligned} \quad (2.4)$$

Here $C \in \mathbb{R}$ and $q \in C^2$ can be chosen arbitrarily.

3) A general form of R easily follows by condition (2.3):

$$\left(R(x, 0, 0) = p(x) > 0 \right) \Rightarrow \left(R(x, y, z) = p(x) + [\rho(x, y, z) - \rho(x, 0, 0)] \right), \quad (2.5)$$

where $p(x) > 0$, $p \in C^2$; $\rho \in C^2$ can be chosen arbitrarily.

4) A general form of the integrand f follows now from (2.1), (2.4) and (2.5):

$$\begin{aligned} f(x, y, z) &= P(x, y) + \left(C + \int_a^x P_y(t, 0) dt + [q(x, y) - q(x, 0)] \right) \cdot z + \\ &\quad + \frac{1}{2} \left(p(x) + [\rho(x, y, z) - \rho(x, 0, 0)] \right) \cdot z^2, \end{aligned} \quad (2.6)$$

where $C \in \mathbb{R}$; $q, p \in C^2$ ($p > 0$) can be chosen arbitrarily. So, the following statement is proved.

Theorem 3. *Let, under the conditions of Theorem 1, functional (1.1) attain a local minimum at zero under the strengthened Legendre condition. Then the integrand f takes the form (2.6).*

Remark 1. *As it follows from Theorem 3, a general form of the variational functional (1.1) taking a local minimum at zero under the strengthened Legendre condition is*

$$\begin{aligned} \Phi(y) &= \int_a^b \left(P(x, y) + \left[C + \int_a^x P_y(t, 0) dt + q(x, y) - q(x, 0) \right] \cdot y' + \right. \\ &\quad \left. + \frac{1}{2} \left[p(x) + \rho(x, y, y') - \rho(x, 0, 0) \right] \cdot y'^2 \right) dx, \end{aligned} \quad (2.7)$$

where $C \in \mathbb{R}$, $P, q, p > 0$, ρ are the arbitrary functions in C^2 .

Thus, under the strengthened Legendre condition, the inverse extremal variational problem at zero is solved: all the functionals of type (1.1) taking a local minimum at zero are described.

Now, let us pass to the general case of an arbitrary C^2 -smooth extremal in $C^1[a; b]$.

Let us fix an arbitrary C^2 -smooth function $y_0(x)$, $a \leq x \leq b$, satisfying the boundary conditions $y(a) = y_0(a)$, $y(b) = y_0(b)$.

In order to reduce the problem to the case of the zero extremal considered above, it suffices to introduce the auxiliary variational functional:

$$\begin{aligned} \tilde{\Phi}(y) = \Phi(y + y_0) &= \int_a^b f(x, y + y_0(x), y' + y'_0(x)) dx =: \int_a^b \tilde{f}(x, y, y') dx \\ &(y(a) = y(b) = 0). \end{aligned}$$

The condition $y_0(\cdot) \in C^2$ guarantees fulfilment of the condition in (1.1) for the auxiliary integrand \tilde{f} .

Application of Theorem 3 to the auxiliary integrand \tilde{f} leads to a solution of the inverse extremal problem for Φ at an arbitrary point $y_0(\cdot) \in C^2[a; b]$.

Theorem 4. *Let, under the conditions of Theorem 1, the variational functional (1.1) attain a local minimum at a point $y_0(\cdot) \in C^2[a; b]$ satisfying the boundary conditions $y(a) = y_0(a)$, $y(b) = y_0(b)$ and the strengthened Legendre condition. Then the integrand f has form*

$$\begin{aligned} f(x, y, z) &= P(x, y - y_0(x)) + \\ &+ \left(C + \int_a^x P_y(t, -y_0(t)) dt + [q(x, y - y_0(x)) - q(x, -y_0(x))] \right) \cdot (z - y'_0(x)) + \\ &+ \frac{1}{2} \left(p(x) + [\rho(x, y - y_0(x), z - y'_0(x)) - \rho(x, -y_0(x), -y'_0(x))] \right) \cdot (z - y'_0(x))^2, \quad (2.8) \end{aligned}$$

where $C \in \mathbb{R}$; $P, q, p > 0$, $\rho \in C^2$ can be chosen arbitrarily.

This implies the following formula for the general form of functional (1.1) attaining a local minimum in $C^1[a; b]$ at a point $y_0(\cdot) \in C^2[a; b]$ under the strengthened Legendre condition:

$$\begin{aligned} \Phi(y) &= \int_a^b \left(P(x, y - y_0(x)) + \left[C + \int_a^x P_y(t, -y_0(t)) dt + q(x, y - y_0(x)) - q(x, -y_0(x)) \right] \cdot \right. \\ &\quad \cdot (y' - y'_0(x)) + \frac{1}{2} \left[p(x) + \rho(x, y - y_0(x), y' - y'_0(x)) - \right. \\ &\quad \left. \left. - \rho(x, -y_0(x), -y'_0(x)) \right] \cdot (y' - y'_0(x))^2 \right) dx, \quad (2.9) \end{aligned}$$

where $C \in \mathbb{R}$; $P, q, p > 0$, $\rho \in C^2$ can be chosen arbitrarily, arises.

Thus, under the strengthened Legendre condition, the inverse extremal variational problem at an arbitrary point $y_0(\cdot) \in C^2$ is solved: all functionals of type (1.1), attaining a local minimum at a point $y_0(\cdot)$, are described.

3 Compact extrema of variational functionals in Sobolev space $H^1[a; b]$

To consider the inverse extremal problem in $H^1[a; b]$, let us first introduce the concept of a compact extremum and bring a necessary information on compact extrema of variational functionals in $H^1[a; b]$.

In the Hilbert-Sobolev space $W^{1,2}[a; b] = H^1[a; b]$ equipped with the norm

$$\|y\|_{H^1[a; b]}^2 = \int_a^b (y^2 + y'^2) dx, \quad (3.1)$$

as is well known, by virtue of I.V. Skrypnik's theorem ([14], Ch.11) variational functionals have practically no non-absolute local extrema. In the our works [11], [9], [10], [6] and in the works by E.V. Bozhonok [1], [2], [3] the general concept of a *compact extremum* (or *K-extremum*) of a functional was studied (see, also, [12]). It has been shown there that the classical, both necessary and sufficient conditions of a local extremum of a variational functional in $C^1[a; b]$ can be extended to the case of a *K-extremum* in $H^1[a; b]$. In this case, the *K-extrema* inherit the important properties of the local extrema and can be considered as an analogue of the ones in the case of variational functionals in $H^1[a; b]$.

Definition 5. Let a real functional $\Phi : H \rightarrow \mathbb{R}$ be defined in a Hilbert space H . Say that Φ has a compact minimum (or *K-minimum*) at a point $y_0 \in H$ if, for each absolutely convex (a.c.) compact set $C \subset H$, the restriction of f to the subspace $(y_0 + \text{span } C)$ has a local minimum at y_0 with respect to the Banach norm $\|\cdot\|_C$ in $\text{span } C$ generated by C . In other words, for each a.c. compactum $C \subset H$ there exists such $\varepsilon = \varepsilon(C) > 0$ that $\varphi(y) \geq \varphi(y_0)$ for all y satisfying $y - y_0 \in \varepsilon \cdot C$.

Next assume for simplicity $[a; b] = [0; T]$.

Definition 6. We say that a mapping $\varphi : [0; T] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}^n$ belongs to the Weierstrass class $W_K(z)$, if φ is uniformly continuous and bounded locally in x and y , and globally in z . We say that φ belongs to the Weierstrass class $W_K^1(z)$ if $\varphi \in W_K(z)$ and gradient $\nabla_{yz}\varphi \in W_K(z)$. We say that φ belongs to the Weierstrass class $W_K^2(z)$ if $\varphi \in W_K(z)$, the gradient $\nabla_{yz}\varphi \in W_K(z)$ and the Hessian $H_{yz}\varphi \in W_K(z)$.

Next, we say that a function $f : [0; T] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ belongs to the class $WK_2(z)$ if a representation pseudoquadratic in z

$$f(x, y, z) = A(x, y, z) + B(x, y, z) \cdot z + C(x, y, z) \cdot z^2, \quad (3.2)$$

can be chosen in such a way that the coefficients A, B, C belong to the class $W_K(z)$. We say that f belongs to the Weierstrass class $W^1K_2(z)$ if the coefficients A, B, C belong to the class $W_K^1(z)$. Finally, we say that f belongs to the Weierstrass class $W^2K_2(z)$ if the coefficients A, B, C belong to the class $W_K^2(z)$.

Note that the classes $W_K(z), W_K^1(z), W_K^2(z)$ can be considered as the appropriate space with dominating mixed smoothness (see [13], [15]).

In [7] the following sufficient condition of the twice K -differentiability of a variational functional in Sobolev space $H^1[0; T]$ was obtained.

Theorem 5. *If $f \in W^2K_2(z)$ then the Euler-Lagrange functional*

$$\Phi(y) = \int_0^T f(x, y, y') dx, \quad y(\cdot) \in H^1[0; T] \quad (3.3)$$

is twice K -differentiable everywhere on $H^1[0; T]$. Moreover,

$$\Phi_K''(y)(h, k) = \int_0^T \left[\frac{\partial^2 f}{\partial y^2} h \cdot k + \frac{\partial^2 f}{\partial y \partial z} (h' \cdot k + h \cdot k') + \frac{\partial^2 f}{\partial z^2} h' \cdot k' \right] dx. \quad (3.4)$$

The following *generalized Euler-Lagrange equation* [1] serves for finding a K -extremum of functional (3.3) in the space $H^1[0; T]$ as an analogue of the classical necessary condition of a local extremum for a variational functional in $C^1[0; T]$.

Theorem 6. *Let, in addition to the hypotheses of Theorem 5, the following conditions hold:*

- (i) *functional (3.3) possesses a K -extremum at a point $y(\cdot) \in H^1[0; T]$;*
- (ii) *the function $\frac{\partial f}{\partial z}(x, y, y')$ is absolutely continuous on $[0; T]$.*

Then the *generalized Euler-Lagrange equation*:

$$L(f)(y) = \frac{\partial f}{\partial y}(x, y, y') - \frac{d}{dx} \left(\frac{\partial f}{\partial z}(x, y, y') \right) = 0 \quad \text{a.e. on } [0; T] \quad (3.5)$$

holds. In particular, the condition (ii) is fulfilled in the case

$$(\partial f / \partial z) \in C^1([0; T] \times \mathbb{R}^2), \quad y(\cdot) \in W^{2,2}[0; T].$$

The solutions of equation (3.5), satisfying condition (ii) of Theorem 6, are called the K -extremals of functional (3.3) in the space $H^1[0; T]$.

Let us also formulate the *generalized sufficient Legendre-Jacobi condition* [3] of a strong K -extremum in the case of Sobolev space $H^1[0; T]$.

Theorem 7. Let $f : [0; T] \times \mathbb{R}^2 \rightarrow \mathbb{R}$, $f \in W^2K_2(z)$, $y(\cdot)$ be a K -extremal of functional (3.3) in $H_0^1[0; T]$ and the functions $\frac{\partial f}{\partial z}(x, y(x), y'(x))$ and $\frac{\partial^2 f}{\partial y \partial z}(x, y(x), y'(x))$ be absolutely continuous on K -extremal $y(\cdot)$. Suppose that:

1) the strengthened Legendre condition, i.e.

$$\frac{\partial^2 f}{\partial z^2}(x, y(x), y'(x)) > 0$$

is fulfilled everywhere on $[0; T]$;

2) the generalized Jacobi condition is fulfilled, i.e. every solution of the Jacobi equation

$$\begin{aligned} -\frac{d}{dx} \left(\frac{\partial^2 f}{\partial z^2}(x, y(x), y'(x)) u' \right) + \left[-\frac{d}{dx} \left(\frac{\partial^2 f}{\partial y \partial z}(x, y(x), y'(x)) \right) + \right. \\ \left. + \frac{\partial^2 f}{\partial y^2}(x, y(x), y'(x)) \right] u \stackrel{a.e.}{=} 0 \end{aligned} \quad (3.6)$$

in the class $H^1[0; T]$, satisfying the initial conditions $u(0) = 0$, $u'(0) = 1$, does not vanishes for $0 < x \leq T$.

Then Euler-Lagrange functional (3.3) possesses a strong K -minimum at the point $y(\cdot)$.

This theorem allows to extend the results of Section 1 to the case of a K -minimum in $H^1[a; b]$.

Theorem 8. Let variational functional (1.1) at a $W^{2,2}$ -smooth point $y_0(\cdot) \in H^1[a; b]$ satisfy the Euler-Lagrange equation, and, in addition, $R(x, y, z) \in W_K^2(z)$.

Then, under the conditions and notation of Theorem 1,

- 1) for $p > 0$, $q \geq 0$, $\Phi(y)$ attains a strong K -minimum at $y_0(\cdot)$ (without any restriction on the length of $[a; b]$);
- 2) for $p > 0$, $q < 0$, and under restriction (1.3) on the length of $[a; b]$, $\Phi(y)$ attains a strong K -minimum at $y_0(\cdot)$ as well.

Theorem 9. Let, under the conditions and notation of Theorem 8, variational functional (1.1) attain a K -minimum at a $W^{2,2}$ -smooth point $y_0(\cdot)$ from $H^1[a; b]$ satisfying the boundary conditions $y(a) = y_0(a)$, $y(b) = y_0(b)$ and the strengthened Legendre condition.

Then the integrand f takes form (2.8), where $C \in \mathbb{R}$; P , q , $p > 0$, in C^2 and ρ in $W_K^2(z)$ can be chosen arbitrarily.

This results implies formula (2.9) giving the general form of functional (1.1) having a K -minimum at a $W^{2,2}$ -smooth point $y_0(\cdot)$ in $H^1[a; b]$ satisfying the strengthened Legendre condition.

4 Minimal pseudoquadratic representation for integrands of variational functionals from the class $W^2K_2(z)$

This Section is devoted to description of a suitable class of integrands for which the corresponding variational functionals in $H^1[a; b]$ possess the compact–analytical properties allowing analytical investigation of a compact extremum.

Let us consider an integrand $f \in W^2K_2(z)$, i.e.

$$f(x, y, z) = A(x, y, z) + B(x, y, z) \cdot z + C(x, y, z) \cdot z^2,$$

where $A, B, C \in W_K(z)$, with analogous representations for the gradient $\nabla_{yz}f$ and the Hessian $H_{yz}f$.

Since the function f is twice continuously differentiable on $\Omega \times \mathbb{R} \times \mathbb{R}$ in (y, z) , application of the second order Taylor formula in z at a point $(x, y, 0)$ leads to

$$f(x, y, z) = f(x, y, 0) + \frac{\partial f}{\partial z}(x, y, 0) \cdot z + \frac{\partial^2 f}{\partial z^2}(x, y, 0) \cdot \frac{z^2}{2} + \varphi(x, y, z), \quad (4.1)$$

where $\varphi(x, y, z) = o(z^2)$ as $z \rightarrow 0$ locally uniformly in x, y . Set

$$R(x, y, z) = \frac{\partial^2 f}{\partial z^2}(x, y, 0) + \frac{\varphi(x, y, z)}{z^2} \quad \text{as } z \neq 0; \quad R(x, y, 0) = 0.$$

Then $R \in W_K(z)$ and, denoting by $P(x, y) = f(x, y, 0)$, $Q(x, y) = \frac{\partial f}{\partial z}(x, y, 0)$, we obtain from (4.1)

$$f(x, y, z) = P(x, y) + Q(x, y) \cdot z + R(x, y, z) \cdot \frac{z^2}{2}, \quad (4.2)$$

where $P, Q \in C^2$; $R \in W_K(z)$.

Now, using the equalities

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial P}{\partial y} + \frac{\partial Q}{\partial y} \cdot z + \frac{\partial R}{\partial y} \cdot \frac{z^2}{2}, & \frac{\partial f}{\partial z} &= Q + R \cdot z + \frac{\partial R}{\partial z} \cdot \frac{z^2}{2}, \\ \frac{\partial^2 f}{\partial y \partial z} &= \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial y} \cdot z + \frac{\partial^2 R}{\partial y \partial z} \cdot \frac{z^2}{2}, & \frac{\partial^2 f}{\partial y^2} &= \frac{\partial^2 P}{\partial y^2} + \frac{\partial^2 Q}{\partial y^2} \cdot z + \frac{\partial^2 R}{\partial y^2} \cdot \frac{z^2}{2}, \\ & & \frac{\partial^2 f}{\partial z^2} &= R + 2 \frac{\partial R}{\partial z} \cdot z + \frac{\partial^2 R}{\partial z^2} \cdot \frac{z^2}{2}, \end{aligned} \quad (4.3)$$

it follows by the conditions

$$\nabla_{yz}f \in WK_2(z), \quad H_{yz}f \in WK_2(z)$$

that

$$\nabla_{yz}R \in W_K(z), \quad H_{yz}R \in W_K(z).$$

Thus, in the representation (4.2), $R \in W_K^2(z)$.

Conversely, if representation (4.2) holds with $P, Q \in C^2$; $R \in W_K^2(z)$, then the condition $f \in W^2K_2(z)$ holds automatically. Thus, the following theorem is proved.

Theorem 10. *The representability of f in form (4.2) with $P, Q \in C^2$; $R \in W_K^2(z)$, is necessary and sufficient for f to be in the class $W^2K_2(z)$.*

5 Stationary form of the Legendre-Jacobi conditions

A simple example of the “harmonic oscillator” in which case

$$\Phi(y) = \int_0^T (y'^2 - y^2) dx$$

shows that restriction (1.3) on the length of $[a; b]$ in Theorem 8(2) can be too strong. Now we consider some types of integrands for which an essential weakening of the restriction (3) is possible.

Let us consider the variational functional

$$\Phi(y) = \int_0^T \left(R(x, y, y') \cdot \frac{y'^2}{2} + Q(x, y) \cdot y' + P(x, y) \right) dx, \quad y(\cdot) \in H_0^1[0; T], \quad (5.1)$$

where $P, Q \in C^2$; $R \in W_K^2(z)$.

Note that, according to Theorem 10, the integrand

$$f(x, y, z) = R(x, y, z) \cdot \frac{z^2}{2} + Q(x, y) \cdot z + P(x, y)$$

is of the class $W^2K_2(z)$. Hence, by Theorem 5, this functional is well-posed and twice K -differentiable in $H_0^1[0; T]$.

Now, consider conditions ensuring existence of a K -extremum at zero for variational functional (5.1).

1) From equalities (4.3) we obtain

$$\frac{\partial f}{\partial y}(x, 0, 0) = \frac{\partial P}{\partial y}(x, 0), \quad \frac{\partial f}{\partial z}(x, 0, 0) = Q(x, 0). \quad (5.2)$$

Then, substituting (5.2) in the Euler-Lagrange variational equation along K -extremal $y_0(x) \equiv 0$ ($0 \leq x \leq T$) for functional (5.1) and taking into account, that $f \in C^2$, we obtain

$$(d/dx)[f(x, 0, 0)] = (d/dx)[Q(x, 0)],$$

hence

$$\frac{\partial P}{\partial y}(x, 0) - \frac{\partial Q}{\partial x}(x, 0) \equiv 0. \quad (5.3)$$

2) Next, let us study conditions of fulfilment of the generalized Legendre-Jacobi sufficient condition for a strong K -extremum of the functional $\Phi(y)$ in Sobolev space H_0^1 (Theorem 7) along a K -extremal $y_0(\cdot)$. Note first that it is necessary to impose the additional requirement of the absolute continuity along the K -extremal $y_0(x) \equiv 0$ of the functions

$$\frac{\partial f}{\partial z}(x, y_0(x), y'_0(x)) = Q(x, 0) \quad \text{and} \quad \frac{\partial^2 f}{\partial y \partial z}(x, y_0(x), y'_0(x)) = \frac{\partial Q}{\partial y}(x, 0).$$

i) *The strengthened Legendre condition* in the case of a K -minimum for functional (5.1) takes the form

$$\frac{\partial^2 f}{\partial z^2}(x, 0, 0) = R(x, 0, 0) > 0 \quad (5.4)$$

everywhere along $[0; T]$.

ii) *The Jacobi condition*: the generalized Jacobi equation for functional (5.1) along K -extremal $y_0(\cdot)$

$$-\frac{d}{dx} \left[\frac{\partial^2 f}{\partial z^2}(x, 0, 0)u' \right] + \left[-\frac{d}{dx} \left(\frac{\partial^2 f}{\partial y \partial z}(x, 0, 0) \right) + \frac{\partial^2 f}{\partial y^2}(x, 0, 0) \right] u \stackrel{\text{a.e.}}{=} 0$$

in view of equalities (5.1) takes the form

$$-\frac{d}{dx} [R(x, 0, 0)u'] + \left[-\frac{d}{dx} \left(\frac{\partial Q}{\partial y}(x, 0) \right) + \frac{\partial^2 P}{\partial y^2}(x, 0) \right] u \stackrel{\text{a.e.}}{=} 0.$$

Or, taking into account $f \in C^2$, it follows that

$$-\frac{d}{dx} [R(x, 0, 0)u'] + \left[\frac{\partial^2 P}{\partial y^2}(x, 0) - \frac{\partial^2 Q}{\partial x \partial y}(x, 0) \right] u \stackrel{\text{a.e.}}{=} 0, \quad (5.5)$$

under the initial conditions $u(0) = 0$, $u'(0) = 1$.

Now, let us consider sufficient conditions of fulfillment of the Jacobi condition.

Assume that the following additional conditions are satisfied

$$R(x, 0, 0) \equiv r > 0, \quad (5.6)$$

$$\left(\frac{\partial^2 P}{\partial y^2} - \frac{\partial^2 Q}{\partial x \partial y} \right) (x, 0) \equiv p. \quad (5.7)$$

Then equation (5.5) takes the form

$$ru'' - pu = 0, \quad u(0) = 0, \quad u'(0) = 1. \quad (5.8)$$

Consider all the possible cases: $p = 0$, $p > 0$, $p < 0$.

a) $p = 0$. Equation (5.8) takes the form: $u'' = 0$, whence the solution $u(x) = x$ satisfies the Jacobi condition:

$$u(x) \neq 0, \quad 0 < x \leq T, \quad \text{for all } T > 0.$$

b) $p > 0$. Equation (5.8) takes the form: $u'' = \frac{p}{r}u$ with $\frac{p}{r} > 0$, whence the solution $u(x) = \sqrt{\frac{r}{p}} \operatorname{sh} \sqrt{\frac{p}{r}} x$ satisfies the Jacobi condition:

$$u(x) \neq 0, \quad 0 < x \leq T, \quad \text{for all } T > 0.$$

c) $p < 0$. Equation (5.8) takes the form: $u'' = -\left|\frac{p}{r}\right|u$ with $\frac{p}{r} < 0$, whence the solution $u(x) = \sqrt{\left|\frac{r}{p}\right|} \sin \sqrt{\left|\frac{p}{r}\right|x}$ satisfies the Jacobi condition:

$$u(x) \neq 0, \quad 0 < x \leq T, \quad \text{only for the case}$$

$$T < \pi \sqrt{\left|\frac{r}{p}\right|}.$$

We say that conditions (5.3), (5.6), (5.7) (providing fulfilment of the Legendre-Jacobi sufficient conditions at zero) are the *stationary form of the Legendre-Jacobi conditions at zero*, or *(SLJ)-conditions*.

Now, let consider some generalization of the conditions (SLJ). Namely, replace the conditions (5.6)–(5.7) by the following ones:

$$R(x, 0, 0) = r \cdot e^{\alpha x} \quad (r > 0, \alpha \in \mathbb{R}), \quad (5.9)$$

$$\left(\frac{\partial^2 P}{\partial y^2} - \frac{\partial^2 Q}{\partial x \partial y} \right) (x, 0) = p \cdot e^{\alpha x}. \quad (5.10)$$

Then equation (5.5) takes the form

$$r \cdot u'' + (r\alpha) \cdot u' - p \cdot u = 0, \quad u(0) = 0, \quad u'(0) = 1, \quad (5.11)$$

with the discriminant

$$D = r(r\alpha^2 + 4p).$$

Consider all the possible cases: $r\alpha^2 + 4p = 0$, $r\alpha^2 + 4p > 0$, $r\alpha^2 + 4p < 0$.

a) $r\alpha^2 + 4p = 0$. The characteristic equation for equation (5.11) takes the form: $\lambda = -\alpha/2$, whence the solution $u(x) = x \cdot e^{-\alpha x/2}$ satisfies the Jacobi condition:

$$u(x) \neq 0, \quad 0 < x \leq T, \quad \text{for all } T > 0.$$

b) $r\alpha^2 + 4p > 0$. The characteristic equation for equation (5.11) takes the form:

$$r \cdot \lambda^2 + (r\alpha) \cdot \lambda - p = 0 \quad (D > 0),$$

whence the solution

$$u(x) = 2e^{-\frac{\alpha}{2}x} \cdot \sqrt{\frac{r}{r\alpha^2 + 4p}} \cdot \text{sh} \left(\frac{1}{2} \sqrt{\frac{r\alpha^2 + 4p}{r}} x \right)$$

satisfies the Jacobi condition:

$$u(x) \neq 0, \quad 0 < x \leq T, \quad \text{for all } T > 0.$$

c) $r\alpha^2 + 4p < 0$. The characteristic equation for equation (5.11) takes the form:

$$r \cdot \lambda^2 + (r\alpha) \cdot \lambda - p = 0 \quad (D < 0),$$

whence the solution

$$u(x) = 2e^{-\frac{\alpha}{2}x} \cdot \sqrt{\frac{r}{|r\alpha^2 + 4p|}} \cdot \sin\left(\frac{1}{2}\sqrt{\frac{|r\alpha^2 + 4p|}{r}}x\right)$$

satisfies the Jacobi condition:

$$u(x) \neq 0, \quad 0 < x \leq T, \quad \text{only for the case}$$

$$T < 2\pi\sqrt{\frac{r}{|r\alpha^2 + 4p|}}.$$

We call conditions (5.9)–(5.10) *the exponential (SLJ)-conditions*. Of course, the “usual” (SLJ)-conditions (5.6)–(5.7) are a particular case of conditions (5.9)–(5.10) corresponding to $\alpha = 0$.

6 Inverse extremal problem for variational functionals in $H^1[a; b]$ under the (SLJ)–condition

Our aim in this Section is to describe *all* integrands of the class $W^2K_2(z)$ satisfying conditions (5.3), (5.6), (5.7):

$$\frac{\partial P}{\partial y}(x, 0) - \frac{\partial Q}{\partial x}(x, 0) \equiv 0, \quad \left(\frac{\partial^2 P}{\partial y^2} - \frac{\partial^2 Q}{\partial x \partial y}\right)(x, 0) \equiv p, \quad R(x, 0, 0) \equiv r > 0, \quad (6.1)$$

where P, Q, R are coefficients of minimal representation (5.1) of the integrand f ; $P, Q \in C^2$; $R \in W_K^2(z)$.

1) Choose $P(x, y) \in C^2$ arbitrarily. Then the first of equations (6.1) leads to:

$$\left(\frac{\partial Q}{\partial x}(x, 0) = \frac{\partial P}{\partial y}(x, 0)\right) \Leftrightarrow \left(Q(x, 0) = \int_0^x \frac{\partial P}{\partial y}(t, 0)dt + C_1\right),$$

hence it follows

$$Q(x, y) = \int_0^x \frac{\partial P}{\partial y}(t, 0)dt + \tilde{Q}(x, y), \quad \text{where } \tilde{Q}(x, 0) \equiv C_1. \quad (6.2)$$

2) The second of equations (6.1) leads to:

$$\frac{\partial^2 Q}{\partial x \partial y}(x, 0) = \frac{\partial^2 P}{\partial y^2}(x, 0) - p. \quad (6.3)$$

Substituting of (6.2) in (6.3) leads to:

$$\left(\frac{\partial^2 \tilde{Q}}{\partial x \partial y}(x, 0) = \frac{\partial^2 Q}{\partial x \partial y}(x, 0) = \frac{\partial^2 P}{\partial y^2}(x, 0) - p\right) \Rightarrow$$

$$\Rightarrow \left(\frac{\partial \tilde{Q}}{\partial y}(x, 0) = \int_0^x \left[\frac{\partial^2 P}{\partial y^2}(t, 0) - p \right] dt + C_2 \right),$$

hence

$$\frac{\partial \tilde{Q}}{\partial y}(x, y) = \int_0^x \left[\frac{\partial^2 P}{\partial y^2}(t, 0) - p \right] dt + \tilde{q}(x, y), \quad \text{where } \tilde{q}(x, 0) \equiv C_2.$$

Now, by integrating in y we obtain:

$$\tilde{Q}(x, y) = \int_0^y ds \int_0^x \left[\frac{\partial^2 P}{\partial y^2}(t, 0) - p \right] dt + \int_0^y \tilde{q}(x, s) ds + C_1, \quad \text{where } \tilde{q}(x, 0) \equiv C_2. \quad (6.4)$$

Next, by substituting (6.4) in (6.2) we obtain:

$$Q(x, y) = \int_0^x \frac{\partial P}{\partial y}(t, 0) dt + \int_0^y ds \int_0^x \left[\frac{\partial^2 P}{\partial y^2}(t, 0) - p \right] dt + \int_0^y \tilde{q}(x, s) ds + C_1,$$

where $\tilde{q}(x, 0) \equiv C_2$. From here, denoting $\tilde{q}(x, y) = q(x, y) - q(x, 0) + C_2$, after not complicated transformations we obtain:

$$\begin{aligned} Q(x, y) = \int_0^x \left[\frac{\partial P}{\partial y}(t, 0) + y \cdot \frac{\partial^2 P}{\partial y^2}(t, 0) \right] dt + \\ + \int_0^y [q(x, s) - q(x, 0)] ds + (C_1 + C_2 y - p \cdot xy), \quad (6.5) \end{aligned}$$

where the function $q \in C^2$ and the constants C_1 and C_2 can be chosen arbitrarily.

3) By setting

$$R(x, y, z) = r(x, y, z) - r(x, 0, 0) + r, \quad (6.6)$$

we obtain the last of conditions (6.1): $R(x, 0, 0) \equiv r$ as well. At last, substituting of (6.5)–(6.6) in (4.2) leads to the desired result:

$$\begin{aligned} f(x, y, z) = P(x, y) + \left\{ \int_0^x \left[\frac{\partial P}{\partial y}(t, 0) + y \cdot \frac{\partial^2 P}{\partial y^2}(t, 0) \right] dt + \int_0^y [q(x, s) - q(x, 0)] ds + \right. \\ \left. + (C_1 + C_2 y - p \cdot xy) \right\} \cdot z + [r(x, y, z) - r(x, 0, 0) + r] \cdot \frac{z^2}{2}, \quad (6.7) \end{aligned}$$

where the functions $P(x, y) \in C^2$, $q(x, y) \in C^2$, $r(x, y, z) \in W_K^2(z)$ and the constants C_1 and C_2 can be chosen arbitrarily.

Let us pass now to the case of an arbitrary K -extremal $y_0(x)$ of the class $W^{2,2}[a; b]$. In this case we, use the auxiliary variational functional (see Introduction):

$$\tilde{\Phi}(y) = \Phi(y + y_0) = \int_a^b f(x, y + y_0(x), y' + y_0'(x)) dx =: \int_a^b \tilde{f}(x, y, y') dx.$$

Applying to \tilde{f} representation (6.7) together with the consequent shifts $y + y_0 \mapsto y$ and $z + y'_0(x) \mapsto z$ leads to the general form of the integrand for the case under consideration:

$$\begin{aligned} f(x, y, z) = & P(x, y - y_0(x)) + \left\{ \int_0^x \left[\frac{\partial P}{\partial y}(t, 0) + (y - y_0(x)) \cdot \frac{\partial^2 P}{\partial y^2}(t, 0) \right] dt + \right. \\ & + \int_0^{y-y_0(x)} [q(x, s) - q(x, 0)] ds + (C_1 + C_2 \cdot (y - y_0(x)) - p \cdot x \cdot (y - y_0(x))) \cdot (z - y'_0(x)) + \\ & \left. + [r(x, y - y_0(x), z - y'_0(x)) - r(x, 0, 0) + r] \cdot \frac{(z - y'_0(x))^2}{2}, \right. \end{aligned}$$

where the functions

$$P(x, y) \in C^2, \quad q(x, y) \in C^2, \quad r(x, y, z) \in W_K^2(z)$$

and the constants C_1 and C_2 can be chosen arbitrarily.

Finally, let us obtain an analogue of representation (6.7) for the case of exponential (SLJ)-conditions:

$$\left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right) (x, 0) \equiv 0; \quad \left(\frac{\partial^2 P}{\partial y^2} - \frac{\partial^2 Q}{\partial x \partial y} \right) (x, 0) = p \cdot e^{\alpha x}; \quad R(x, 0, 0) = r \cdot e^{\alpha x} \quad (r > 0).$$

Choosing $P(x, y) \in C^2$ arbitrarily and acting analogously with 1)–2) above, we can obtain

$$\begin{aligned} Q(x, y) = & \int_0^x \left[\frac{\partial P}{\partial y}(t, 0) + y \cdot \frac{\partial^2 P}{\partial y^2}(t, 0) \right] dt + \\ & + \int_0^y [q(x, s) - q(x, 0)] ds + \left(C_1 + C_2 y - p \cdot \frac{e^{\alpha x} - 1}{\alpha} \cdot y \right), \end{aligned}$$

where the functions $P(x, y) \in C^2$, $q \in C^2$ and the constants C_1 and C_2 can be chosen arbitrarily.

Next, by setting

$$R(x, y, z) = r(x, y, z) - r(x, 0, 0) + r \cdot e^{\alpha x}$$

and acting analogously to 3) above, we can obtain the desired result:

$$\begin{aligned} f(x, y, z) = & P(x, y) + \left\{ \int_0^x \left[\frac{\partial P}{\partial y}(t, 0) + y \cdot \frac{\partial^2 P}{\partial y^2}(t, 0) \right] dt + \right. \\ & \left. + \int_0^y [q(x, s) - q(x, 0)] ds + \left(C_1 + C_2 y - p \cdot \frac{e^{\alpha x} - 1}{\alpha} \cdot y \right) \right\} \cdot z + \end{aligned}$$

$$+ [r(x, y, z) - r(x, 0, 0) + r \cdot e^{\alpha x}] \cdot \frac{z^2}{2},$$

where the functions

$$P(x, y) \in C^2, \quad q(x, y) \in C^2, \quad r(x, y, z) \in W_K^2(z)$$

and the constants C_1 and C_2 can be chosen arbitrarily.

7 Properties of mappings of class $W_K^2(z)$

Aiming at applying formulas (6.7) where the mappings $R(x, y, z) \in W_K^2(z)$, we consider some properties of the such mappings.

First, denote by $W^2(z)$ the class of the mappings $\varphi(z)$ having $\varphi(z)$, $\varphi'(z)$ and $\varphi''(z)$ possessing uniform continuity and boundedness for $-\infty < z < \infty$. Then the following statements are valid.

Proposition 3. *If*

$$R(x, y, z) = \sum_{k=1}^n \alpha_k(x, y) \cdot \beta_k(z), \quad \text{where } \alpha_k \in C^2, \quad \beta_k \in W^2(z),$$

then $R \in W_K^2(z)$.

Proof. Let us fix $k = \overline{1, n}$. As $\alpha_k(x, y)$ is uniformly continuous and bounded in x, y by the Weierstrass theorem, and $\beta_k(z)$ is uniformly continuous globally in z by the assumption, then obviously $\alpha_k(x, y) \cdot \beta_k(z) \in W_K(z)$.

Next, the gradient

$$\nabla_{yz}[\alpha_k(x, y) \cdot \beta_k(z)] = \left(\frac{\partial \alpha_k}{\partial y}(x, y) \cdot \beta_k(z), \alpha_k(x, y) \cdot \beta_k'(z) \right)$$

has the coefficients from $W_K(z)$ and therefore is in that class. Finally, the Hessian

$$H_{yz}[\alpha_k(x, y) \cdot \beta_k(z)] = \begin{pmatrix} \frac{\partial^2 \alpha_k}{\partial y^2}(x, y) \cdot \beta_k(z), & \frac{\partial \alpha_k}{\partial y} \cdot \beta_k'(z) \\ \frac{\partial \alpha_k}{\partial y}(x, y) \cdot \beta_k'(z), & \alpha_k(x, y) \cdot \beta_k''(z) \end{pmatrix}$$

has the coefficients in $W_K(z)$ as well and therefore is in that class. So, $\alpha_k(x, y) \cdot \beta_k(z) \in W_K^2(z)$, hence $R(x, y, z) \in W_K^2(z)$ evidently follows. \square

Proposition 4. *If $R_1, \dots, R_m \in W_K^2(z)$; $\varphi(u_1, u_2, \dots, u_m) \in C^2$, then $\varphi(R_1(x, y, z), \dots, R_m(x, y, z)) \in W_K^2(z)$.*

Proof. For an arbitrary compact $C_y \subset \mathbb{R}$ the mappings R_1, \dots, R_m are uniformly continuous and bounded on $[0; T] \times C_y \times \mathbb{R}$. Hence φ possesses the same properties on the set

$$\prod_{i=1}^m R_i([0; T] \times C_y \times \mathbb{R})$$

and therefore the composition $\varphi(R_1, \dots, R_m)$ is in the Weierstrass class $W_K(z)$. The analogous properties of $\nabla_{yz}\varphi(R_1, \dots, R_m)$ and $H_{yz}\varphi(R_1, \dots, R_m)$ follow from the representations

$$\begin{aligned} \frac{\partial}{\partial y}\varphi(R_1, \dots, R_m) &= \sum_{i=1}^m \frac{\partial\varphi}{\partial u_i}(R_1, \dots, R_m) \cdot \frac{\partial R_i}{\partial y}; \\ \frac{\partial}{\partial z}\varphi(R_1, \dots, R_m) &= \sum_{i=1}^m \frac{\partial\varphi}{\partial u_i}(R_1, \dots, R_m) \cdot \frac{\partial R_i}{\partial z}; \\ \frac{\partial^2}{\partial y^2}\varphi(R_1, \dots, R_m) &= \\ &= \sum_{i=1}^m \left[\sum_{j=1}^m \frac{\partial^2\varphi}{\partial u_i \partial u_j}(R_1, \dots, R_m) \cdot \frac{\partial R_j}{\partial y} \cdot \frac{\partial R_i}{\partial y} + \frac{\partial\varphi}{\partial u_i}(R_1, \dots, R_m) \cdot \frac{\partial^2 R_i}{\partial y^2} \right]; \\ \frac{\partial^2}{\partial z^2}\varphi(R_1, \dots, R_m) &= \\ &= \sum_{i=1}^m \left[\sum_{j=1}^m \frac{\partial^2\varphi}{\partial u_i \partial u_j}(R_1, \dots, R_m) \cdot \frac{\partial R_j}{\partial z} \cdot \frac{\partial R_i}{\partial z} + \frac{\partial\varphi}{\partial u_i}(R_1, \dots, R_m) \cdot \frac{\partial^2 R_i}{\partial z^2} \right]; \\ \frac{\partial^2}{\partial y \partial z}\varphi(R_1, \dots, R_m) &= \\ &= \sum_{i=1}^m \left[\sum_{j=1}^m \frac{\partial^2\varphi}{\partial u_i \partial u_j}(R_1, \dots, R_m) \cdot \frac{\partial R_j}{\partial z} \cdot \frac{\partial R_i}{\partial y} + \frac{\partial\varphi}{\partial u_i}(R_1, \dots, R_m) \cdot \frac{\partial^2 R_i}{\partial y \partial z} \right]. \end{aligned}$$

□

Corollary 1. *By the conditions $R_1, \dots, R_m \in W_K^2(z)$, $\alpha_k(x, y) \in C^2$ ($k = \overline{1, m}$) it follows that*

$$\sum_{k=1}^m \alpha_k(x, y) R_k(x, y, z) \in W_K^2(z).$$

Note that the last Corollary generalizes Proposition 3 because

$$\beta_k \in W^2(z) \Rightarrow \beta_k \in W_K^2(z).$$

Corollary 2. *If $R_1, \dots, R_m \in W_K^2(z)$, then $R_1 \cdot R_2 \cdot \dots \cdot R_m \in W_K^2(z)$.*

Proposition 5. *If $R(x, y, z) \in W_K^2(z)$, $\psi(z) \in W^2(z)$ then $R(x, y, \psi(z)) \in W_K^2(z)$.*

Proof. Since for an arbitrary compact C_y the mapping R is uniformly continuous and bounded on $[0; T] \times C_y \times \mathbb{R}$ and ψ is uniformly continuous and bounded for $z \in \mathbb{R}$, then $R(x, y, \psi(z))$ is of the Weierstrass class $W_K(z)$. The analogous properties of $\nabla_{yz}R(x, y, \psi(z))$ and $H_{yz}R(x, y, \psi(z))$ follow from the representations

$$\frac{\partial}{\partial y}R(x, y, \psi(z)) = \frac{\partial R}{\partial y}(x, y, \psi(z)); \quad \frac{\partial}{\partial z}R(x, y, \psi(z)) = \frac{\partial R}{\partial z}(x, y, \psi(z)) \cdot \psi'(z);$$

$$\begin{aligned}\frac{\partial^2}{\partial y^2}R(x, y, \psi(z)) &= \frac{\partial^2 R}{\partial y^2}(x, y, \psi(z)); & \frac{\partial}{\partial y \partial z}R(x, y, \psi(z)) &= \frac{\partial^2 R}{\partial y \partial z}(x, y, \psi(z)) \cdot \psi'(z); \\ \frac{\partial^2}{\partial z^2}R(x, y, \psi(z)) &= \frac{\partial^2 R}{\partial z^2}(x, y, \psi(z)) \cdot (\psi'(z))^2 + \frac{\partial R}{\partial z}(x, y, \psi(z)) \cdot \psi''(z).\end{aligned}$$

□

Let us note also some properties of the class $W^2(z)$ being used in the constructions above. Denote by $C_b^n(z)$ the class of all functions $\varphi(z) \in C^n$ having bounded derivatives up to n -th order.

Property 1. *The following inclusions are valid:*

$$C_b^3(z) \subset W^2(z) \subset C_b^2(z).$$

Property 2. *If $\varphi \in C^2$ and φ is periodic, then $\varphi \in W^2(z)$.*

Property 3. *If $\varphi \in C^2$, $\varphi^{(k)}$ ($\pm\infty$) exist and are finite for $k = 0, 1, 2$, then $\varphi \in W^2(z)$.*

8 Non-local K -extrema of variational functionals in $H^1[a; b]$

Here we describe a rather wide class of the variational functionals in $H^1[a; b]$ having a non-local compact extremum at zero.

Note first, that if functional (5.1) attains a strong K -minimum at zero then for every zero neighborhood $U(0) \subset H^1$ there exist such values of y that $\Phi(y) > \Phi(0)$. Thus, Φ cannot attain a local maximum at zero.

Now, let us investigate conditions under which functional (5.1) does not attain a local minimum at zero.

Let the integrand of functional (5.1) satisfy conditions (6.1) i.e., it takes form (6.7) and let Φ attain a strong K -minimum at zero. Suppose for convenience $\Phi(0) = 0$. By virtue of (6.7), it means

$$\int_0^T P(x, 0) dx = 0.$$

The last condition is obviously satisfied under the assumption

$$P(x, 0) \equiv 0. \quad (8.1)$$

Introduce also the supplementary conditions:

$$Q(0, 0) = 0, \quad (8.2)$$

that is equivalent, by virtue of (6.7), to the condition $C_1 = 0$, and also the alternating signs condition for R :

$$R(x, 0, z_0) \leq -r_0 < 0 \quad (\forall x \in [0; T]) \quad (8.3)$$

for some z_0 . Let us show that Φ does not attain a local minimum at zero under conditions (8.1)–(8.3).

Set

$$y^\varepsilon(x) = \begin{cases} z_0(x - \varepsilon), & \text{as } 0 \leq x \leq \varepsilon; \\ 0, & \text{as } \varepsilon \leq x \leq T \end{cases}$$

for sufficiently small $\varepsilon > 0$.

Obviously, $y^\varepsilon \in H_0^1[0; T]$. Moreover,

$$\|y^\varepsilon\|_{H^1}^2 = \int_0^\varepsilon (z_0^2(x - \varepsilon)^2 + z_0^2) dx = z_0^2 \left(\varepsilon + \frac{\varepsilon^3}{3} \right) \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

The integrand f along the function y^ε takes the form

$$\begin{aligned} & f(x, y^\varepsilon, (y^\varepsilon)') = \\ & = \begin{cases} R(x, z_0(x - \varepsilon), z_0) \cdot \frac{z_0^2}{2} + Q(x, z_0(x - \varepsilon)) \cdot z_0 + P(x, z_0(x - \varepsilon)), & 0 \leq x \leq \varepsilon; \\ 0, & \varepsilon \leq x \leq T. \end{cases} \end{aligned}$$

From here it follows that

$$\begin{aligned} \Phi(y^\varepsilon) &= \frac{z_0^2}{2} \cdot \int_0^\varepsilon R(x, z_0(x - \varepsilon), z_0) dx + \\ &+ z_0 \cdot \int_0^\varepsilon Q(x, z_0(x - \varepsilon)) dx + \int_0^\varepsilon P(x, z_0(x - \varepsilon)) dx. \quad (8.4) \end{aligned}$$

Moreover,

$$\begin{cases} (8.1) \text{ implies} & P(x, z_0(x - \varepsilon)) = o(1) \\ (8.2) \text{ implies} & Q(x, z_0(x - \varepsilon)) = o(1) \\ (8.3) \text{ implies} & R(x, z_0(x - \varepsilon), z_0) = -r_0 + o(1) \end{cases} \quad \text{as } \varepsilon \rightarrow 0. \quad (8.5)$$

From (8.4)–(8.5) it follows that

$$\Phi(y^\varepsilon) = o(\varepsilon) + z_0 \cdot o(\varepsilon) + \frac{z_0^2}{2} \cdot [o(\varepsilon) - r_0\varepsilon] = -\frac{z_0^2 r_0}{2} \varepsilon + o(\varepsilon) < 0$$

for sufficiently small $\varepsilon > 0$.

Thus, functional (5.1) cannot attain a local minimum at zero and therefore it does not attain a local extremum at zero. Hence, an arbitrary variational functional $\Phi(y)$ having an integrand satisfying conditions (6.1) and (8.1)–(8.3), attains a non-local K -minimum at zero. Let us summarize the results of our considerations.

Theorem 11. Consider a functional of the form

$$\Phi(y) = \int_0^T \left(R(x, y, y') \cdot \frac{y'^2}{2} + Q(x, y) \cdot y' + P(x, y) \right) dx, \quad y(\cdot) \in H_0^1[0; T],$$

where $P, Q \in C^2; R \in W_K^2(z)$.

Then under the assumptions:

$$\frac{\partial P}{\partial y}(x, 0) - \frac{\partial Q}{\partial x}(x, 0) \equiv 0, \quad \left(\frac{\partial^2 P}{\partial y^2} - \frac{\partial^2 Q}{\partial x \partial y} \right)(x, 0) \equiv p, \quad R(x, 0, 0) \equiv r > 0,$$

$$P(x, 0) \equiv 0, \quad Q(0, 0) = 0,$$

and also under the alternating signs condition for R :

$$R(x, 0, z_0) \leq -r_0 < 0 \quad (\forall x \in [0; T]);$$

for some z_0 , the variational functional $\Phi(y)$ attains a non-local K -minimum at zero for every $T > 0$ in the case of $p \geq 0$ and for $0 < T < \pi \sqrt{\left| \frac{r}{p} \right|}$ in the case of $p < 0$.

Let us consider in the conclusion some concrete examples.

Example 1. Consider the following functional:

$$\Phi(y) = \int_0^{1/3} \left((y')^2 \left(\sin(1 + \cos y') - \frac{1}{2} \right) + y' \sin y^2 + y^2 \right) dx, \quad y(\cdot) \in H_0^1([0; 1/3]).$$

In the case under consideration,

$$P(y) = y^2, \quad Q(y) = \sin y^2, \quad R(z) = 2 \sin(1 + \cos z) - 1.$$

Direct calculation shows fulfilment of condition (6.1) and (8.1)–(8.3) for the functional $\Phi(y)$. Moreover,

$$R(0) \equiv r = 2 \sin 2 - 1 > 0,$$

and for $z = \pi$ $R(\pi) = -1 < 0$.

Thus, since in the case $p \equiv 2 > 0$ and $T = 1/3$, then by virtue of Theorem 11 the functional $\Phi(y)$ attains a non-local K -minimum at zero.

Example 2. Consider the following functional:

$$\Phi(y) = \int_0^1 \left(y^3 \ln(x^2 + 4) + y' \sin xy + \frac{(y')^2 \cos y'}{2(1 + (y')^2)} \right) dx, \quad y(\cdot) \in H_0^1[0; 1].$$

In the case under consideration

$$P(x, y) = y^3 \ln(x^2 + 4), \quad Q(x, y) = \sin xy, \quad R(z) = \frac{\cos z}{1 + z^2}.$$

Direct calculation shows fulfilment of conditions (6.1) and (8.1)–(8.3) for the functional $\Phi(y)$. Moreover,

$$R(0) \equiv r = 1 > 0,$$

and for $z = \pi$ $R(\pi) = -1/(1 + \pi^2) < 0$.

Thus, since in the case $p \equiv -1 < 0$ and $T = 1 < \pi$, then by virtue of Theorem 11 the functional $\Phi(y)$ attains a non-local K -minimum at zero.

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