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THE SMALL PARAMETER METHOD FOR REGULAR LINEAR DIFFERENTIAL EQUATIONS ON UNBOUNDED DOMAINS

G.A. Karapetyan, H.G. Tananyan

Communicated by V.I. Burenkov

Key words: regular operator, hypoelliptic operator, boundary layer, regular degeneration, singular perturbation, uniform solvability.

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Abstract. Algorithms for the asymptotic expansion of the solution to the Dirichlet problem for a regular equation with a small parameter ε ($\varepsilon > 0$) at higher derivatives on an unbounded domain (the whole space, the half space and a strip), based on the solution to the degenerate (as $\varepsilon \to 0$) Dirichlet problem for a regular hypoelliptic equation of the lower order, are described. Estimates for remainder terms of those expansions are obtained.

Introduction

The degeneration of the Dirichlet problem $\mathfrak{D}_{\varepsilon}$ for a regular (in the sense of Mikhailov - Nikol'skii [10], [11], [13]-[15]) equation with a small parameter ε ($\varepsilon > 0$) at higher derivatives to the Dirichlet problem \mathfrak{D}_0 for a regular hypoelliptic equation (introduced by Hörmander [5]) in the Sobolev anisotropic spaces $\mathbb{W}_2^{\mathscr{M}}(G)$ (generated by a regular polyhedron \mathscr{M} and by unbounded domain G) is considered. The methods for constructing the asymptotic expansion of the solution to Problem $\mathfrak{D}_{\varepsilon}$ based on Lindshted-Poincare's method, Prandell's boundary layer method (for references and for more details about those methods see [1], [6], [7], [8], [12], [19], [22]), Lusternik-Vishik's method [23] and Newton's polyhedron method [21] are described.

Note that the degenerate Problem \mathfrak{D}_0 can be solved by Bubnov-Galerkin's method (see Ghazaryan and Karapetyan [3]) by choosing anisotropic B-splines as base functions (see [18]).

1 Basic notation and terminology

Throughout the paper, we use the following standard notation: \mathbb{N} is the set of all natural numbers, $\mathbb{N}_0 \equiv \mathbb{N} \cup \{0\}$, \mathbb{R} is the set of all real numbers. For $n \in \mathbb{N}$, $x = (x_1, ..., x_n) \in \mathbb{R}^n$, $\alpha = (\alpha_1, ..., \alpha_n) \in \mathbb{N}_0^n$, $\beta = (\beta_1, ..., \beta_n) \in \mathbb{N}_0^n$, $\mathscr{M} \subset \mathbb{N}_0^n$ and $\xi = (\xi_1, ..., \xi_n) \in \mathbb{R}^n$ we denote

$$|x| = (x_1^2 + ... + x_n^2)^{\frac{1}{2}}, x^{(j)} = (x_1, ..., x_{j-1}, x_{j+1}, ..., x_n) (1 \le j \le n),$$

$$\alpha! = \alpha_1! ... \alpha_n!, \qquad |\alpha| = \alpha_1 + ... + \alpha_n, \qquad \beta \leq \alpha \Leftrightarrow \beta_j \leq \alpha_j \ (1 \leq j \leq n),$$

$$\binom{\alpha}{\beta} = \frac{\alpha!}{\beta! (\alpha - \beta)!} \ (\beta \leq \alpha), \qquad \alpha\beta = \alpha_1\beta_1 + ... + \alpha_n\beta_n,$$

$$\mathscr{M}^2 \equiv \mathscr{M} \times \mathscr{M} \equiv \{(\alpha, \beta) : \alpha, \beta \in \mathscr{M}\},$$

$$\mathscr{M} + \mathscr{M} \equiv \{\alpha + \beta : \alpha, \beta \in \mathscr{M}\},$$

$$\xi^{\alpha} = \xi_1^{\alpha} ... \xi_n^{\alpha}, \qquad D^{\alpha} = D_1^{\alpha_1} ... D_n^{\alpha_n},$$

where $D_j = \frac{\partial}{\partial x_j}$ $(1 \le j \le n)$.

We denote by $\mathbb{C}(G)$ the space of all functions f uniformly continuous on the domain $G \subset \mathbb{R}^n$ with the norm

$$||f||_{\mathbb{C}(G)} \equiv \sup_{x \in G} |f(x)|.$$

$$\mathbb{W}_{2}^{(p)}(\Omega) = \left\{ f \in \mathbb{L}_{P}(\Omega) : \sum_{|\alpha| \le p} \|D^{\alpha} f\|_{\mathbb{L}_{p}(\Omega)} < \infty \right\}.$$

For a finite set of multi-indices $\mathcal{M} \subset \mathbb{N}_0^n$ and a domain $G \subseteq \mathbb{R}^n$ we also denote

$$\mathbb{W}_{2}^{\mathscr{M}}(G) \equiv \left\{ f \in \mathbb{L}_{2}(G) : \|f\|_{\mathbb{W}_{2}^{\mathscr{M}}(G)} \equiv \sum_{\alpha \in \langle \mathscr{M} \cup \{0\} \rangle} \|D^{\alpha} f\|_{\mathbb{L}_{2}(G)} < \infty \right\},$$

where $\langle \mathcal{M} \bigcup \{0\} \rangle$ is the convex hull of the collection $\mathcal{M} \bigcup \{0\}$, and by $\check{\mathbb{H}}_{\mathcal{M}}(G)$ we denote the closure of the set $\mathbb{C}_0^{\infty}(G)$ with respect to the norm $\|.\|_{\mathbb{W}_2^{\mathcal{M}}(G)}$. Let ∂G be the boundary of G, let Ξ be Nikol'skii's skeleton (see [14]) of the collection $\langle \mathcal{M} \bigcup \{0\} \rangle$ and

$$\mathring{\mathbb{W}}_{2}^{\mathscr{M}}(G) \equiv \left\{ f \in \mathbb{W}_{2}^{\mathscr{M}}(G) : D^{\alpha} f|_{\partial G} = 0, \quad \forall \alpha \in \Xi \right\}.$$

In a Hilbert space \mathbb{H} the inner product will be denoted by $(.,.)_{\mathbb{H}}$. We consider only real function spaces.

2 Setting of the problem

Let $\Omega \subset \mathbb{R}^n$ be a domain, $\mathscr{N} \subset \mathbb{N}_0^n$ and $\mathscr{N}_0 \subset \mathscr{N}$ be finite collections of multi-indices, $\overline{\varepsilon} \in (0,1)$. Let ψ be a non-negative function defined on $\mathscr{N} \times \mathscr{N}$, and let

$$L_{\varepsilon} \equiv L_{\varepsilon}(x, D) \equiv \sum_{\alpha, \beta \in \mathcal{N}} \varepsilon^{\psi(\alpha, \beta)} D^{\alpha} \left(\eta_{\alpha, \beta}(x, \varepsilon) D^{\beta} \right) \qquad (\eta_{\alpha, \beta}(x, \varepsilon) \not\equiv 0, \ \alpha, \beta \in \mathcal{N})$$
(2.1)

and

$$L_{0} \equiv L_{0}(x, D) \equiv \sum_{\alpha, \beta \in \mathcal{N}_{0}} D^{\alpha} \left(\eta_{\alpha, \beta}(x, 0) D^{\beta} \right) \qquad (\eta_{\alpha, \beta}(x, 0) \not\equiv 0, \ \alpha, \beta \in \mathcal{N}_{0})$$
 (2.2)

be linear differential operators with real-valued coefficients defined on $\overline{\Omega} \times [0, \overline{\varepsilon}]$. Consider the following boundary problems: **Problem** \mathfrak{D}_0 . Find a solution $u \in \mathring{\mathbb{W}}_2^{\mathscr{N}_0}(\Omega)$ to the equation

$$L_0 u = h, \qquad h \in \mathbb{W}_2^{\infty}(\Omega) \equiv \bigcap_{p=1}^{\infty} \mathbb{W}_2^{(p)}(\Omega).$$
 (2.3)

Problem $\mathfrak{D}_{\varepsilon}$. Find a solution $u_{\varepsilon} \in \mathring{\mathbb{W}}_{2}^{\mathscr{N}}(\Omega)$ to the equation

$$L_{\varepsilon}u_{\varepsilon} = h, \qquad h \in \mathbb{W}_{2}^{\infty}(\Omega).$$
 (2.4)

In the sequel the following notation will be used:

$$\varphi\left(\nu\right) \equiv \min_{\substack{\alpha,\beta \in \mathcal{N} \\ \alpha+\beta=\nu}} \psi\left(\alpha,\beta\right) \qquad \nu \in \mathcal{N} + \mathcal{N},$$

and

$$\varphi_{\mathcal{M}}^{opt}\left(\alpha^{0}\right) \equiv \min \left\{ q \in \mathbb{R} : \forall \varepsilon \in (0, \overline{\varepsilon}], \forall \xi \in \mathbb{R}^{n}, \xi \geq \mathbf{0}, \varepsilon^{q} \xi^{\alpha^{0}} \leq \sum_{\alpha \in \mathcal{M}} \varepsilon^{\varphi(\alpha)} \xi^{\alpha} \right\}$$
(2.5)

for $\mathcal{M} \subseteq \mathcal{N} + \mathcal{N}$, $\alpha^0 \in \langle \mathcal{M} \rangle$.

We impose the following restrictions on the operators L_0 and L_{ε}

- (A₁) a) the functions $\eta_{\alpha,\beta}(x,\varepsilon)$ ($\alpha,\beta\in\mathscr{N}$) are infinitely differentiable on $\overline{\Omega}\times[0,\overline{\varepsilon}]$;
- b) for each $\alpha, \beta \in \mathcal{N}_0$ the functions $\eta_{\alpha,\beta}(x,\varepsilon)$ tend to $\eta_{\alpha,\beta}(x,0)$ as $\varepsilon \to 0$ uniformly with respect to x;
 - c) for each $\alpha, \beta \in \mathcal{N}_0 \ \psi(\alpha, \beta) = 0$;
 - (A_2) there exists a constant $\chi_1 > 0$ such that

$$(L_0 w, w) \ge \chi_1 \sum_{\alpha \in \mathcal{N}_0 \cup \{0\}} \|D^{\alpha} w\|^2 \qquad \forall w \in \mathbb{C}_0^{\infty} (\Omega);$$

$$(2.6)$$

- (A₃) $\{\gamma \in \mathbb{N}_0^n : \gamma \leq \alpha\} \subseteq \langle \mathcal{N} \cup \{0\} \rangle$ for all $\alpha \in \mathcal{N}$;
- (A₄) a) the functions $\eta_{\alpha,\beta}(x,\varepsilon)$ are uniformly continuous with respect to x on $\Omega \times (0,\overline{\varepsilon}]$, for $(\alpha,\beta) \in \mathcal{R} \equiv \{(\alpha,\beta) \in \mathcal{N}^2 \setminus \mathcal{N}_0^2 : |\alpha+\beta| \equiv 0 \, (mod2)\}$;
 - b) there exists a constant $\kappa_1 > 0$ such that

$$|\eta_{\alpha,\beta}(x,\varepsilon)| \le \kappa_1 \quad \forall x \in \Omega, \forall \varepsilon \in (0,\overline{\varepsilon}], (\alpha,\beta) \in \mathscr{R};$$

c) there exists a constant $\chi_2 > 0$ such that

$$\sum_{(\alpha,\beta)\in\overline{\mathscr{R}}}\varepsilon^{\psi(\alpha,\beta)}\eta_{\alpha,\beta}\left(x,0\right)\left(\mathrm{i}\xi\right)^{\alpha+\beta}\geq\chi_{2}\sum_{\alpha\in\mathscr{B}}\varepsilon^{\varphi_{\mathscr{N}+\mathscr{N}}^{opt}\left(2\alpha\right)}\xi^{2\alpha}\qquad\forall\xi\in\mathbb{R}^{n},\forall\varepsilon\in\left(0,\overline{\varepsilon}\right],$$

where

$$\overline{\mathcal{R}} \equiv \left\{ (\alpha, \beta) \in \mathcal{R} : \varphi(\alpha + \beta) = \varphi_{\mathcal{N} + \mathcal{N}}^{opt}(\alpha + \beta) \right\},
\mathcal{V} \equiv \left\{ \alpha \in \mathcal{N} \setminus \mathcal{N}_0 : \alpha \notin \langle (\mathcal{N} \setminus \mathcal{N}_0) \setminus \{\alpha\} \rangle \right\},
\mathcal{B} \equiv \mathcal{V} \cup \left\{ \alpha \in (\mathcal{N} \setminus \mathcal{N}_0) \setminus \mathcal{V} : \varphi_{(\mathcal{N} \setminus \mathcal{N}_0) \setminus \{\alpha\}}^{opt}(\alpha) > \varphi_{\mathcal{N} \setminus \mathcal{N}_0}^{opt}(\alpha) \right\};$$

d) there exists a constant $\kappa_3 > 0$ such that for every $(\alpha, \beta) \in \mathscr{I} \equiv \{(\alpha, \beta) \in \mathscr{N}^2 \setminus \mathscr{N}_0^2 : |\alpha + \beta| \equiv 1 \pmod{2}\}$ and $\gamma, \delta \in \mathbb{N}_0^n$, if $\gamma \leq \alpha, \delta \leq \beta$ and $\gamma + \delta \neq \alpha + \beta$,

$$|D^{\gamma+\delta}\eta_{\alpha,\beta}(x,\varepsilon)| \le \kappa_3 \qquad x \in \Omega, \varepsilon \in (0,\overline{\varepsilon}];$$

(A₅) for every $\alpha, \beta \in \mathcal{N} + \mathcal{N}, \alpha \leq \beta, \alpha \neq \beta$

$$\varphi_{\mathcal{N}+\mathcal{N}}^{opt}\left(\alpha\right) < \varphi_{\mathcal{N}+\mathcal{N}}^{opt}\left(\beta\right);$$

 (A_6) for every $(\alpha, \beta) \in \mathcal{N} \times \mathcal{N} \quad \psi(\alpha, \beta) \in \mathbb{N}_0$.

3 Solvability and uniform solvability

Definition 3.1. Problem \mathfrak{D}_0 is said to be solvable if for every $h \in \mathbb{L}_2(\Omega)$ the equation $L_0 u = h$ has a unique solution $u_0 \in \mathring{\mathbb{W}}_2^{\mathscr{N}_0}(\Omega)$ such that

$$||u_0||_{\mathbb{W}_2^{\mathscr{N}_0}(\Omega)} \le C ||h||_{\mathbb{L}_2(\Omega)}$$

for some constant C > 0 independent of h.

Remark 3.1. (see [13], [14] and [11]). Let Ω be the whole space, the half space or a strip. Then Problem \mathfrak{D}_0 is solvable if Condition (A_2) holds. If $h \in \mathbb{W}_2^{\infty}(\Omega)$ then the solution w_0 to Problem \mathfrak{D}_0 is smooth, i.e. $u_0 \in \mathbb{W}_2^{\infty}(\Omega)$ (see [16]) and hence $D^{\alpha}u_0 \in \mathbb{C}(\overline{\Omega})$ for any $\alpha \in \mathbb{N}_0^n$ by the known embedding theorem (see [2], §9).

Definition 3.2. (see [23]). Problem $\mathfrak{D}_{\varepsilon}$ is said to be uniformly solvable if there exists a number $\varepsilon_0 > 0$ for which

- a) Problem $\mathfrak{D}_{\varepsilon}$ is solvable for $\varepsilon \in (0, \varepsilon_0]$, i.e., for every $h \in \mathbb{L}_2(\Omega)$ the equation $L_{\varepsilon}u = h$ has a unique solution $u_{\varepsilon} \in \mathring{\mathbb{W}}_2^{\mathscr{N}}(\Omega)$;
- b) there exists a number $C_0 > 0$, and for each $\varepsilon \in (0, \varepsilon_0]$ a normed function space $B_{\varepsilon} \left(\mathring{\mathbb{W}}_{2}^{\mathscr{N}} (\Omega) \subset B_{\varepsilon} \right)$ with the norm $\|.\|_{B_{\varepsilon}}$ such that for all $h \in L_2(\Omega)$

$$||u_{\epsilon}||_{B_{\varepsilon}} \le C_0 ||h||_{\mathbb{L}_2(\Omega)}, \qquad \varepsilon \in (0, \varepsilon_0].$$

Remark 3.2. (see [13], [14] and [11]). Let Ω be the whole space, the half space or a strip. Then Problem $\mathfrak{D}_{\varepsilon}$ is solvable for any fixed $\varepsilon \in (0, \varepsilon_0]$ if Conditions $(A_1) - (A_4)$ hold.

Theorem 3.1. (see [14] and [4]). Let Ω be the whole space, the half space or a strip. If Condition (A_3) holds then $\mathring{\mathbb{W}}_2^{\mathcal{N}}(\Omega) = \mathring{\mathbb{H}}_{\mathcal{N}}(\Omega)$.

Theorem 3.2. (see [20]). Let $\mathcal{N} \subset \mathbb{N}_0^n$, $\langle \mathcal{N} \rangle$ be a completely regular polyhedron, $\Omega \subset \mathbb{R}^n$ be a bounded domain satisfying the shift conditions (for example, see [2] or [4]), and the operator L_{ε} satisfy Conditions $(A_1) - (A_6)$. Then Problem $\mathfrak{D}_{\varepsilon}$ is uniformaly solvable. Moreover, there exist constants $\overline{\overline{\varepsilon}} \in (0, \overline{\varepsilon}]$ and $C_1 > 0$ such that for all $u \in \mathring{\mathbb{W}}_2^{\mathcal{N}}(\Omega)$

$$||u||_{\varepsilon}^{2} \equiv \sum_{\alpha \in \langle \mathcal{N} \rangle \setminus \langle \mathcal{N}_{0} \rangle} \varepsilon^{\varphi_{\mathcal{N}+\mathcal{N}}^{opt}(2\alpha)} ||D^{\alpha}u||^{2} + \sum_{\alpha \in \langle \mathcal{N}_{0} \cup \{0\} \rangle} ||D^{\alpha}u||^{2} \leq C_{1}(L_{\varepsilon}u, u) \qquad \forall \varepsilon \in (0, \overline{\varepsilon}].$$

4 Poincare method on \mathbb{R}^n

Theorem 4.1. Let $\Omega = \mathbb{R}^n$, $m \in \mathbb{N}_0$ and

- **I.** a) Conditions (A_1) and (A_6) hold;
- b) the coefficients $\eta_{\alpha,\beta}(x,\varepsilon)$ ($\alpha,\beta\in\mathcal{N}$) of the operator L_{ε} are bounded together with their derivatives in x_n up to order m+1 on $\mathbb{R}^n\times[0,\overline{\varepsilon}]$;
 - II. a) Problem \mathfrak{D}_0 is solvable;
 - b) the solution w_0 of Problem \mathfrak{D}_0 is smooth, i.e. $w_0 \in \mathbb{W}_2^{\infty}(\mathbb{R}^n)$;
 - III. Problem $\mathfrak{D}_{\varepsilon}$ is uniformly solvable;

Then the solution u_{ε} to Problem $\mathfrak{D}_{\varepsilon}$ admits the following asymptotic expansion:

$$u_{\varepsilon} = w_0 + \sum_{i=1}^{m} \varepsilon^i w_i + z_m, \tag{4.1}$$

where w_0 is the solution to Problem \mathfrak{D}_0 , w_i (i = 1, ..., m) are the solutions to the \mathfrak{D}_0 type problems, and the remainder term z_m satisfies the following estimate:

$$||z_m||_{\varepsilon} = O\left(\varepsilon^{m+1}\right) \tag{4.2}$$

 $(\|.\|_{B_{\varepsilon}} \text{ is the norm in Condition III, see Definition 3.2}).$

Proof. Let $N \in \mathbb{N}_0$. By Condition (A₁,a) the coefficients $\eta_{\alpha,\beta}$ can be represented as a finite power series with respect to ε with the remainder term of the order (N+1):

$$\eta_{\alpha,\beta}\left(x,\varepsilon\right) = \eta_{\alpha,\beta}^{(0)}\left(x\right) + \sum_{i=1}^{N} \varepsilon^{i} \eta_{\alpha,\beta}^{(i)}\left(x\right) + \varepsilon^{N+1} \bar{\eta}_{\alpha,\beta}^{(N+1)}\left(x,\varepsilon\right) \quad \left(\alpha,\beta\in\mathscr{N}\right),\tag{4.3}$$

where

$$\eta_{\alpha,\beta}^{(i)}(x) = \frac{1}{i!} \frac{\partial^{i} \eta_{\alpha,\beta}(x,\epsilon)}{\partial \epsilon^{i}} \bigg|_{\epsilon=0},$$

$$\bar{\eta}_{\alpha,\beta}^{(N+1)}(x,\epsilon) = \frac{1}{(N+1)!} \frac{\partial^{N+1} \eta_{\alpha,\beta}(x,\epsilon)}{\epsilon^{N+1}} \bigg|_{\epsilon=\bar{\epsilon}},$$

$$(\eta_{\alpha,\beta}^{(0)}(x) \equiv \eta_{\alpha,\beta}(x,0)).$$

Then by Conditions (A_1,b) , (A_1,c) and (A_6) .

$$L_{\varepsilon} = \sum_{s=0}^{N} \varepsilon^{s} L^{(s)} + \varepsilon^{N+1} L^{(N+1)}, \tag{4.4}$$

where

$$L^{(0)} \equiv L_0, \qquad L^{(s)} \equiv L^{(s)}(D, x) \equiv \sum_{\substack{\alpha, \beta \in \mathcal{N} \\ 0 \le j \le N \\ \psi(\alpha, \beta) + j = s}} D^{\alpha} \eta_{\alpha, \beta}^{(j)}(x) D^{\beta} \qquad (s = 1, ..., N), \quad (4.5)$$

$$L^{(N+1)} \equiv L^{(N+1)}(D,x,\varepsilon) \equiv \sum_{\substack{\alpha,\beta \in \mathcal{N} \\ 0 \leq s \leq N \\ \psi(\alpha,\beta)+s \geq N+1}} \varepsilon^{\psi(\alpha,\beta)+s-N-1} D^{\alpha} \eta_{\alpha,\beta}^{(s)}\left(x\right) D^{\beta}$$

$$+\sum_{\alpha,\beta\in\mathcal{N}} \varepsilon^{\psi(\alpha,\beta)} D^{\alpha} \bar{\eta}_{\alpha,\beta}^{(N+1)}(x,\varepsilon) D^{\beta}. \tag{4.6}$$

Let N = m and let w_0 be the solution of Problem \mathfrak{D}_0 , and let $w_i \in \mathring{\mathbb{W}}_2^{\mathscr{N}_0}(\mathbb{R}^n)$ (i = 1, ..., m) be the solution of the equation

$$L_0 w_i = -\sum_{s=1}^i L^{(s)} w_{i-s} (4.7)$$

It is obvious that by Condition III

$$w_i \in \mathbb{W}_2^{\infty} \left(\mathbb{R}^n \right) \qquad i = 1, ..., m. \tag{4.8}$$

Denote

$$u^{(m)} \equiv w_0 + \sum_{i=1}^m \varepsilon^i w_i.$$

Thus

$$L_{\varepsilon}u^{(m)} = L_0 w_0 + \sum_{i=1}^m \varepsilon^i \left(L_0 w_i + \sum_{s=1}^i L^{(s)} w_{i-s} \right) + \varepsilon^{N+1} \sum_{i=0}^m \sum_{r=0}^i \varepsilon^{i-r} L^{(N+1-r)} w_i. \tag{4.9}$$

It is not difficult to see (using expressions (4.5) and (4.6), by Conditions I, II and (4.8)) that there exists a number M > 0 such that

$$||L^{(N+1-r)}w_i|| \le M$$
 $(r = 0, ..., i; i = 0, ..., m),$

hence from (4.9) by (4.7) it follows that there exists a number K > 0 such that

$$||L_{\varepsilon}u^{(m)} - h|| \le K\varepsilon^{m+1}.$$

Let u_{ε} be the solution to Problem $\mathfrak{D}_{\varepsilon}$, and let $z_m = u_{\varepsilon} - u^{(m)}$ (it is easy to see that $z_m \in \mathring{\mathbb{W}}_2^{\mathscr{N}}(\mathbb{R}^n)$). Then by Condition III

$$||z_m||_{\varepsilon} \le (L_{\varepsilon}z_m, z_m) = (L_{\varepsilon}u_{\varepsilon}, z_m) - (L_{\varepsilon}u^{(m)}, z_m) = -(L_{\varepsilon}u^{(m)} - h, z_m),$$

so by Cauchy type inequality for any $\omega > 0$

$$\|z_m\|_{\varepsilon} \leq \frac{1}{2} \left(\omega \|L_{\varepsilon}u^{(m)} - h\| + \frac{1}{\omega} \|z_m\| \right),$$

therefore

$$\|z_m\|_{\varepsilon} = O\left(\varepsilon^{m+1}\right).$$

Corollary 4.1. Under Conditions $(A_1) - (A_6)$ the solution u_{ε} admits asymptotic expansion (4.1) where w_0 is the solution of Problem \mathfrak{D}_0 , and $w_i \in \mathring{\mathbb{W}}_2^{\mathscr{N}_0}(\mathbb{R}^n)$ (i = 1, ..., m) is the solution to equation (4.7) and the remainder z_m satisfies estimate (4.2).

5 Regular degeneration

Denote

$$k_n \equiv \max_{\alpha \in \mathcal{N}_0} \alpha_n, \qquad l_n \equiv \max_{\alpha \in \mathcal{N}} \alpha_n - k_n,$$
$$e^n \equiv (0, ..., 0, 1), \qquad q_n \equiv \psi \left((k_n + l_n) e^n, (k_n + l_n) e^n \right).$$

We impose the following additional restriction on the coefficients of the operator L_{ε} .

(A₇) For every $\alpha, \beta \in \mathcal{N} + \mathcal{N}$

$$\psi(\alpha, \beta) \ge \frac{(\alpha_n + \beta_n - 2k_n) q_n}{2l_n} \text{ with } \alpha + \beta = (\alpha_n + \beta_n) e^n,$$

$$\psi(\alpha, \beta) > \frac{(\alpha_n + \beta_n - 2k_n) q_n}{2l_n}$$
 with $\alpha + \beta \neq (\alpha_n + \beta_n) e^n$.

Let $\Omega = \mathbb{R}^n_+ \equiv \{x \in \mathbb{R}^n : x_n > 0\}$, $\varkappa \in \mathbb{N}$, $N \in \mathbb{N}_0$ and $t = x_n \varepsilon^{-\varkappa}$. Then, under Condition (A_1) the coefficients $\eta_{\alpha,\beta}$ can be represented as in formula (4.3), and in addition the functions $\eta_{\alpha,\beta}^{(i)}$ can be represented as a finite power series with respect to x_n :

$$\eta_{\alpha,\beta}^{(i)}\left(x\right) = \eta_{\alpha,\beta}^{(i,0)}\left(x^{(n)}\right) + \sum_{j=1}^{N} x_{n}^{j} \eta_{\alpha,\beta}^{(i,j)}\left(x^{(n)}\right) + x_{n}^{N+1} \bar{\eta}_{\alpha,\beta}^{(i,N+1)}\left(x\right) \qquad \left(\alpha,\beta \in \mathcal{N}; i = 0, 1, ..., N\right),$$

where $\eta_{\alpha,\beta}^{(i,0)}\left(x^{(n)}\right) \equiv \eta_{\alpha,\beta}^{(i)}\left(x^{(n)},0\right)$

Since

$$\frac{\partial^s}{\partial x_n^s} = \varepsilon^{-s\varkappa} \frac{\partial^s}{\partial t^s} \ (s \ge 1) \,,$$

for $\alpha,\beta\in\mathcal{N};i=0,1,...,N;j=0,1,...,N$ we get

$$D_x^{\alpha} \left(x_n^j \eta_{\alpha,\beta}^{(i,j)} \left(x^{(n)} \right) \right) D_x^{\beta} = \varepsilon^{-\varkappa(\alpha_n + \beta_n) + \varkappa j} D_y^{\alpha} \left(t^j \eta_{\alpha,\beta}^{(i,j)} \left(x \right) \right) D_y^{\beta}, \tag{5.1}$$

where $y \equiv (x^{(n)}, t)$.

Using (5.1), the operator L_{ε} can be represented as follows:

$$L_{\varepsilon} = \sum_{\alpha,\beta \in \mathcal{N}} \left(\sum_{i=0}^{N} \left(\sum_{j=0}^{N} \varepsilon^{i-\varkappa(\alpha_{n}+\beta_{n})+\varkappa j+\psi(\alpha,\beta)} D_{y}^{\alpha} \left(t^{j} \eta_{\alpha,\beta}^{(i,j)} \left(x^{(n)} \right) \right) D_{y}^{\beta} + \right.$$

$$\left. + D^{\alpha} \left(x_{n}^{N+1} \bar{\eta}_{\alpha,\beta}^{(i,N+1)}(x) \right) D^{\beta} \right) + \varepsilon^{N+1} D^{\alpha} \bar{\eta}_{\alpha,\beta}^{(N+1)}(x,\varepsilon) D^{\beta} \right).$$

$$(5.2)$$

Denote

$$\gamma \equiv \max_{\alpha,\beta \in \mathcal{N}} \left(\psi \left(\alpha, \beta \right) - \varkappa \left(\alpha_n + \beta_n \right) \right).$$

From (5.2), combining terms with equal powers of ε , we get:

$$L_{\varepsilon} = \varepsilon^{\gamma} \left\{ M_0 + \sum_{s=1}^{N} \varepsilon^s R_s + \varepsilon^{N+1} R_{N+1} \right\}, \tag{5.3}$$

where

$$M_{0} \equiv \sum_{\substack{\alpha,\beta \in \mathcal{N} \\ \psi(\alpha,\beta)-\varkappa(\alpha_{n}+\beta_{n})=\gamma}} D_{y}^{\alpha} \eta_{\alpha,\beta}^{(0,0)}\left(x^{(n)}\right) D_{y}^{\beta} = \sum_{\substack{\alpha,\beta \in \mathcal{N} \\ \psi(\alpha,\beta)-\varkappa(\alpha_{n}+\beta_{n})=\gamma}} D_{y}^{\alpha} \eta_{\alpha,\beta}\left(x^{(n)},0,0\right) D_{y}^{\beta},$$

$$R_{s} \equiv \sum_{\substack{\alpha,\beta \in \mathcal{N} \\ 0 \leq i \leq N, 0 \leq j \leq N \\ \psi(\alpha,\beta)-\varkappa(\alpha_{n}+\beta_{n})+i+\varkappa j=\gamma+s}} D_{y}^{\alpha}\left(t^{j} \eta_{\alpha,\beta}^{(i,j)}\left(x^{(n)}\right)\right) D_{y}^{\beta} \qquad (s = 1, ..., N), \qquad (5.5)$$

and

$$R_{N+1} \equiv \sum_{\substack{\alpha,\beta \in \mathcal{N} \\ 0 \le i \le N, 0 \le j \le N \\ \psi(\alpha,\beta) - \varkappa(\alpha_n + \beta_n) + i + \varkappa j > \gamma + N}} \varepsilon^{i-\varkappa(\alpha_n + \beta_n) + \varkappa j + \psi(\alpha,\beta) - N - 1} D_y^{\alpha} \left(t^j \eta_{\alpha,\beta}^{(i,j)} \left(x^{(n)} \right) \right) D_y^{\beta} + \sum_{\substack{0 \le i \le N, 0 \le j \le N \\ \psi(\alpha,\beta) - \varkappa(\alpha_n + \beta_n) + i + \varkappa j > \gamma + N}} + \sum_{\alpha,\beta \in \mathcal{N}} \varepsilon^{-\gamma} D_x^{\alpha} \left(x_n^{N+1} \bar{\eta}_{\alpha,\beta}^{(i,N+1)} \left(x \right) \right) D_x^{\beta} + \sum_{\alpha,\beta \in \mathcal{N}} \varepsilon^{-\gamma} D_x^{\alpha} \bar{\eta}_{\alpha,\beta}^{(N+1)} \left(x, \varepsilon \right) D_x^{\beta}.$$

Proposition 5.1. For M_0 to be an ordinary differential operator of order $2(k_n + l_n)$ with a minor member of order $2k_n$, it is necessary and sufficient that

$$1^{0}) \gamma = -\frac{k_n q_n}{l_n};$$

In a minor memoer of order
$$2k_n$$
, it is necessary and so 1^0) $\gamma = -\frac{k_n q_n}{l_n}$;
 2^0) $\varkappa = \frac{q_n}{2l_n}$ is a natural number;
 3^0) $\psi(\alpha, \beta) \ge \frac{(\alpha_n + \beta_n - 2k_n)q_n}{2l_n}$ for $\alpha + \beta = (\alpha_n + \beta_n) e^n$,
 $\psi(\alpha, \beta) > \frac{(\alpha_n + \beta_n - 2k_n)q_n}{2l_n}$ for $\alpha + \beta \ne (\alpha_n + \beta_n) e^n$.

Proof. It is easy to see that the derivative $\frac{\partial^{2k_n}}{\partial t^{2k_n}}$ presents in M_0 if and only if $\gamma =$ $\psi(k_n e^n, k_n e^n) - 2\varkappa k_n = -2\varkappa k_n$, and the derivative $\frac{\partial^{2(k_n+l_n)}}{\partial t^{2(k_n+l_n)}}$ presents in M_0 , if and only if $\gamma = \psi((k_n + l_n)e^n, (k_n + l_n)e^n) - 2\varkappa(k_n + l_n) = q - 2\varkappa(k_n + l)$, which are equivalent to conditions 1^0) and 2^0). M_0 was an ordinary differential operator if and only if $\psi(\alpha, \beta) - \varkappa(\alpha_n + \beta_n) > \gamma$ for $\alpha + \beta \neq (\alpha_n + \beta_n) e^n$ and $\psi(\alpha, \beta) - \varkappa(\alpha_n + \beta_n) \geq \gamma$ for $\alpha + \beta = (\alpha_n + \beta_n) e^n$, which are equivalent to condition 3^0).

Remark 5.1. Note that under Condition (A₆) we can assume that $\varkappa = \frac{q_n}{2l_n}$ is a natural number and is equal to 1 (otherwise we can obtain this by the change of the variable).

Remark 5.2. Under Conditions (A_1) , (A_6) and (A_7) (in respect to Remark 5.1) if $\varkappa = \frac{q_n}{2l_n}$ then the operator M_0 is an ordinary differential operator.

Let M_0 (introduced in (5.4)) is an ordinary differential operator and satisfies the conditions of Proposition 5.1. We introduce the following equation (which is the characteristic equation of the operator M_0):

$$\lambda^{2\varkappa k_n}Q\left(\lambda\right) \equiv \lambda^{2\varkappa k_n} \sum_{\substack{\alpha_n e^n, \beta_n e^n \in \mathcal{N} \\ \psi(\alpha_n e^n, \beta_n e^n) - \varkappa(\alpha_n + \beta_n) = \gamma}} \eta_{\alpha_n e^n, \beta_n e^n}\left(x^{(n)}, 0, 0\right) \lambda^{\alpha_n + \beta_n - 2\varkappa k_n} = 0. \quad (5.6)$$

Definition 5.1. The degeneration of the Problem $\mathfrak{D}_{\varepsilon}$ into Problem \mathfrak{D}_{0} is called regular if Conditions (A₁), (A₆) and (A₇) hold and the characteristic polynomial $Q(\lambda)$ has exactly l_{n} pairwise different roots with negative real parts.

Later, we use the following result.

Lemma 5.1. (see Lemma 4 in [23]). Let $m, M \in \mathbb{N}_0$ and let

$$P(t) = \sum_{j=2m}^{2M} a_j t^j \qquad (a_{2m} \neq 0, a_{2M} \neq 0)$$

be a polynomial with real coefficients. If there exists C>0 such that for all $\xi\in\mathbb{R}$

$$Re(P(i\xi)) \equiv \sum_{j=m}^{M} (-1)^{j} a_{2j} \xi^{2j} \ge C(\xi^{2m} + \xi^{2M})$$

then P has exactly (M-m) roots with negative real parts.

For the complete symbol of the operator L_{ε} , we introduce the notation

$$L_{\varepsilon}(x, i\xi) \equiv \sum_{\alpha, \beta \in \mathcal{N}} \varepsilon^{\psi(\alpha, \beta)} \eta_{\alpha, \beta}(x, \varepsilon) (i\xi)^{\alpha + \beta}.$$

Theorem 5.1. Let Conditions (A_1) , $(A_4.c)$, (A_6) and (A_7) hold. Then Q (defined in (5.6)) has exactly l_n roots with negative real parts.

Proof. It follows by Condition (A₄.c) that there is a constant $\chi_2 > 0$ such that for all $\xi_n \in \mathbb{R}$ and $\varepsilon \in (0, \overline{\varepsilon}]$

$$\sum_{(\alpha_n e^n, \beta_n e^n) \in \overline{\mathcal{R}}} \varepsilon^{\psi(\alpha_n e^n, \beta_n e^n)} \eta_{\alpha_n e^n, \beta_n e^n} \left(x^{(n)}, 0, 0 \right) (\mathrm{i}\xi_n)^{\alpha_n + \beta_n} \ge \chi_2 \sum_{\alpha_n e^n \in \mathcal{B}} \varepsilon^{\varphi_{\mathcal{N} + \mathcal{N}}^{opt} (2\alpha_n e^n)} \xi_n^{2\alpha}. \tag{5.7}$$

Clearly,

$$\sum_{\substack{\alpha_n e^n, \beta_n e^n \in \mathcal{N} \\ \psi(\alpha_n e^n, \beta_n e^n) - \varkappa(\alpha_n + \beta_n) = \gamma}} \varepsilon^{\psi(\alpha_n e^n, \beta_n e^n)} \eta_{\alpha_n e^n, \beta_n e^n} \left(x^{(n)}, 0, 0\right) \left(\mathrm{i}\xi_n\right)^{\alpha_n + \beta_n} =$$

$$= \sum_{\substack{\alpha_n e^n, \beta_n e^n \in \mathcal{N} \\ \psi(\alpha_n e^n, \beta_n e^n) - \varkappa(\alpha_n + \beta_n) = \gamma}} \varepsilon^{\gamma} \eta_{\alpha_n e^n, \beta_n e^n} \left(x^{(n)}, 0, 0 \right) \left(\mathbf{i} \xi_n \varepsilon^{\varkappa} \right)^{\alpha_n + \beta_n} = \left(\mathbf{i} \xi_n \right)^{2\varkappa k_n} Q \left(\mathbf{i} \xi_n \varepsilon^{\varkappa} \right).$$

It is not hard to check that

$$Re\left(\mathrm{i}\xi_{n}\right)^{2\varkappa k_{n}}Q\left(\mathrm{i}\xi_{n}\varepsilon^{\varkappa}\right)=\sum_{(\alpha_{n}e^{n},\beta_{n}e^{n})\in\overline{\mathscr{R}}}\varepsilon^{\psi(\alpha_{n}e^{n},\beta_{n}e^{n})}\eta_{\alpha_{n}e^{n},\beta_{n}e^{n}}\left(x^{(n)},0,0\right)\left(\mathrm{i}\xi_{n}\right)^{\alpha_{n}+\beta_{n}}.$$

Then from condition (5.7), by Lemma 5.1, it immediately follows that the polynomial Q has exactly l_n roots with negative real parts.

Remark 5.3. (see [9]). Let $u \in \mathbb{W}_2^{\infty}(\mathbb{R}^n_+)$. For $u \in \mathring{\mathbb{W}}_2^{\mathscr{N}_0}(\mathbb{R}^n_+)$ to be true, it is necessary and sufficient that

$$\frac{\partial^s u}{\partial x_n^s}\Big|_{x_n=0} = 0 \qquad (s = 0, 1, ..., k_n - 1),$$
(5.8)

and for $u \in \mathring{\mathbb{W}}_{2}^{\mathscr{N}}(\mathbb{R}_{+}^{n})$, to be true it is necessary and sufficient conditions (5.8) are satisfied and

$$\frac{\partial^{k_n+s} u}{\partial x_n^{k_n+s}} \bigg|_{x_n=0} = 0 \qquad (s = 0, 1, ..., l_n - 1).$$
(5.9)

6 Boundary layer method on \mathbb{R}^n_+ and on a strip

Definition 6.1. (see [23], p. 7). Let $v_{\varepsilon}(x) = v_{\varepsilon}(x_1, \ldots, x_n)$ be an s $(s \in \mathbb{N})$ times differentiable function in a domain $Q \subset \mathbb{R}^n$. Then v_{ε} is called a boundary layer type function of order k (k < s), if

1. for every closed subset \overline{K} of the domain Q ($\overline{K} \subset Q$), which does not intersect the boundary ∂Q of the domain Q ($\overline{K} \cap \partial Q = \emptyset$) and for every $\delta > 0$ there exists positive number ε_0 such that

$$|D^{\alpha}v_{\varepsilon}(x)| \leq \delta \qquad \forall \varepsilon \in (0, \varepsilon_0], \forall x \in \overline{K}, |\alpha| \leq s;$$

2. there exist positive numbers M and ε_0 such that

$$|D^{\alpha}v_{\varepsilon}(x)| \leq M \qquad \forall \varepsilon \in (0, \varepsilon_0], \forall x \in Q, |\alpha| = k;$$

3. for every $\delta > 0$ there exists positive number ε_0 such that

$$|D^{\alpha}v_{\varepsilon}(x)| \leq \delta \qquad \forall \varepsilon \in (0, \varepsilon_0], \forall x \in \overline{Q}, |\alpha| < k;$$

Example 1. The typical examples of boundary layer type functions of order k on the positive semiaxis are

$$\varepsilon^k e^{-\frac{\lambda t}{\varepsilon}}$$
 and $\varepsilon^k P\left(\frac{t}{\varepsilon}\right) e^{-\frac{\lambda t}{\varepsilon}}$,

where $\lambda > 0$ and P is a polynomial.

Suppose $\tau \in (0, \infty)$, and $\phi(y)$ is an infinitely differentiable function of one variable, that equals to 1 when $y \leq \frac{\tau}{2}$ and vanishes when $y \geq \tau$.

Theorem 6.1. Let $\Omega = \mathbb{R}^n_+$, $m \in \mathbb{N}_0$ and

- I. a) Conditions (A_1) and (A_6) hold;
- b) The coefficients $\eta_{\alpha,\beta}(x,\varepsilon)$ $(\alpha,\beta\in\mathscr{N})$ of the operator L_{ε} are bounded with its derivatives of x_n up to order $m+k_n+1$ on $\overline{\mathbb{R}^n_+}\times[0,\overline{\varepsilon}];$
 - **II.** a) Problem \mathfrak{D}_0 is solvable;
 - b) The solution w_0 of Problem \mathfrak{D}_0 is smooth, i.e. $w_0 \in \mathbb{W}_2^{\infty}(\mathbb{R}_+^n)$;

III. Problem $\mathfrak{D}_{\varepsilon}$ is uniformly solvable;

IV. The degeneration of Problem $\mathfrak{D}_{\varepsilon}$ into Problem \mathfrak{D}_{0} is regular.

Then the solution u_{ε} of Problem $\mathfrak{D}_{\varepsilon}$ admits the following asymptotic expansion:

$$u_{\varepsilon} = w_0 + \sum_{i=1}^{m} \varepsilon^i w_i + \sum_{i=0}^{m+k_n} \varepsilon^i \left(v_i + \varepsilon \phi \left(x_n \right) \alpha_i \right) + z_m,$$

where w_0 is the solution of Problem \mathfrak{D}_0 , w_i (i = 1, ..., m) is the solution of the \mathfrak{D}_0 type problem, $v_i = \varepsilon^{k_n} \overline{v}_i$ $(i = 0, ..., m + k_n)$ is a boundary layer type function of order k_n , α_i $(i = 0, ..., m + k_n)$ is a polynomial of degree $k_n - 1$ with respect to x_n , and for the remainder z_m the following estimate holds:

$$||z_m||_{\varepsilon} = O\left(\varepsilon^{m+1}\right)$$

 $(\|.\|_{\varepsilon} \text{ is the norm in Condition III, see Definition 3.2}).$

The proof of Theorem 6.1 will be given below.

Denoting the roots of the polynomial Q with negative real parts by $-\lambda_1, ..., -\lambda_{l_n}$, by Definition 5.1 we get

$$\lambda_q \neq \lambda_j \qquad (1 \le q \ne j \le l_n).$$
 (6.1)

Proposition 6.1. Let w_0 be a solution of Problem \mathfrak{D}_0 . Under the conditions of Theorem 6.1 there exist functions $c_{0,1} \equiv c_{0,1} \left(x^{(n)}, \varepsilon \right), ..., c_{0,l_n} \equiv c_{0,l_n} \left(x^{(n)}, \varepsilon \right)$ uniformly bounded in \mathbb{R}^n_+ (with respect to ε) with their derivatives in any order such that the functions $(t = x_n \varepsilon^{-1}, x_n = \varepsilon t)$

$$v_0 \equiv \varepsilon^{k_n} \overline{v}_0 \equiv \varepsilon^{k_n} \sum_{s=1}^{l_n} c_{0,s} e^{-\lambda_s t} = \varepsilon^{k_n} \sum_{s=1}^{l_n} c_{0,s} e^{-\lambda_s x_n \varepsilon^{-1}}, \tag{6.2}$$

$$\varepsilon \alpha_0 \equiv -\varepsilon^{k_n} \sum_{q=1}^{l_n} c_{0,q} \sum_{s=0}^{k_n-1} \frac{\left(-\lambda_q t\right)^s}{s!} = -\varepsilon \sum_{q=1}^{l_n} c_{0,q} \sum_{s=0}^{k_r-1} \varepsilon^{k_n-1-s} \frac{\left(-\lambda_q x_n\right)^s}{s!}.$$
 (6.3)

satisfy the following conditions

- 1) v_0 is a boundary layer type function of the order k_n ;
- 2) the function $w_0 + v_0 + \varepsilon \alpha_0$ satisfies the boundary conditions of Problem $\mathfrak{D}_{\varepsilon}$.

Proof. Statement 1. We keep the requirement that $w_0 + v_0$ has to satisfy conditions (5.9), i.e.

$$\frac{\partial^{k_n+s} \left(w_0 + \varepsilon^{k_n} \overline{v}_0 \right)}{\partial x_n^{k_n+s}} \bigg|_{x_n=0} = 0 \qquad (s = 0, 1, ..., l_n - 1).$$
(6.4)

By Condition II.b in Theorem 6.1 and Remark 3.1, from (6.4) we get

$$\frac{\partial^{k_n+s} \varepsilon^{k_n} \overline{v}_0}{\partial x_n^{k_n+s}} \bigg|_{x_n=0} = -\frac{\partial^{k_n+s} w_0}{\partial x_n^{k_n+s}} \bigg|_{x_n=0} \qquad (s=0,1,...,l_n-1), \tag{6.5}$$

or

$$\frac{\partial^{k_n+s}\overline{v_0}}{\partial t^{k_n+s}}\bigg|_{t=0} = -\varepsilon^s \frac{\partial^{k_n+s}w_0}{\partial x_n^{k_n+s}}\bigg|_{x_n=0} \qquad (s=0,1,...,l_n-1).$$
(6.6)

Substituting representation (6.2) of the function \overline{v}_0 into (6.6), we get a system of l_n linear equations with l_n unknown quantities $c_{0,q} = c_{0,q} \left(x^{(n)}, \varepsilon \right)$:

$$\sum_{q=1}^{l_n} (-\lambda_s)^{k_n+s} c_{0,q} = -\varepsilon^s \frac{\partial^{k_n+s} w_0}{\partial x_n^{k_n+s}} \bigg|_{x_n=0} \qquad (s=0,1,...,l_n-1).$$
 (6.7)

The determinant of this system is of Vandermonde type and it does not vanish by the conditions (6.1).

Consequently, system (6.7) has a unique solution.

Statement 2. The function $-\varepsilon\alpha_0$ is the sum of the first k_n terms of the Taylor series of v_0 in a neighborhood of $x_n = 0$. Therefore, the function $v_0 + \varepsilon\alpha_0$ satisfies boundary conditions (5.8). On the other hand, $\varepsilon\alpha_0$ is a $k_n - 1$ order polynomial of x_n (or of t). Hence, it automatically satisfies conditions (5.9). Besides, w_0 satisfies boundary conditions (5.8) and $w_0 + v_0$ satisfies boundary conditions (5.9), and therefore the function $w_0 + v_0 + \varepsilon\alpha_0$ satisfies boundary conditions (5.8) and (5.9).

Note that functions w_0 , α_0 and their derivatives in any order are uniformly bounded in \mathbb{R}^n_+ (with respect to ε), and $M_0v_0=0$ in \mathbb{R}^n_+ .

Remark 6.1. If d_1, \ldots, d_{l_n} is a solution of the system

$$\begin{cases} \sum_{q=1}^{l_n} (-\lambda_s)^{k_n} d_q = -\frac{\partial^{k_n} w_0}{\partial x_n^{k_n}} \Big|_{x_n=0}, \\ \sum_{q=1}^{l_n} (-\lambda_s)^{k_n+s} d_q = 0 \quad (s = 1, ... l_n - 1). \end{cases}$$

then it is not difficult to see that the solution $c_{0,1}, \ldots, c_{0,l_n}$ to system (6.7) can be represented in the form

$$c_{0,q}(x^{(n)},\varepsilon) = d_q(x^{(n)}) + \sum_{s=1}^{l_r-1} g_{q,s}(x^{(n)}) \varepsilon^s,$$

where $g_{q,s}$ $(q = 1, ..., l_n)$ are some functions independent of ε .

For
$$t \in R$$
 and $1 \le j \le n$ we set $(x^{(j)}, t) \equiv (x_1, ..., x_{j-1}, t, x_{j+1}, ..., x_n)$.

Proposition 6.2. Under the conditions of Theorem 6.1 there exist functions $c_{i,1} \equiv c_{i,1}(x^{(n)},t,\varepsilon),...,c_{i,l_n} \equiv c_{i,l_n}(x^{(n)},t,\varepsilon)$ ($0 < i \le m+k_n$) uniformly bounded on \mathbb{R}^n_+ (with respect to ε) with their derivatives of any order such that the functions

$$v_i \equiv \varepsilon^{k_n} \overline{v}_i \equiv \varepsilon^{k_n} \sum_{q=1}^{l_n} c_{i,q} e^{-\lambda_q t},$$
 (6.8)

and

$$\varepsilon \alpha_{i} \equiv -\varepsilon^{k_{n}} \sum_{q=1}^{l_{n}} c_{i,q} \left(x^{(n)}, t, \varepsilon \right) \sum_{s=0}^{k_{n}-1} \frac{\left(-\lambda_{q} t \right)^{s}}{s!} =$$

$$= -\varepsilon \sum_{q=1}^{l_{n}} c_{i,q} \left(x^{(n)}, t, \varepsilon \right) \sum_{s=0}^{k_{n}-1} \varepsilon^{k_{n}-1-s} \frac{\left(-\lambda_{q} x_{n} \right)^{s}}{s!}. \tag{6.9}$$

satisfy the following conditions

1) α_i and their derivatives of any order uniformly bounded on \mathbb{R}^n_+ (with respect to ε)

2) the solution $w_i \in \mathring{\mathbb{W}}_2^{\mathcal{N}_0}(\mathbb{R}^n_+)$ (i = 1, ..., m) of the equation

$$L_0 w_i = h_i \equiv -\sum_{s=1}^{i} L^{(s)} w_{i-s} - \sum_{s=0}^{i-1} L^{(s)} \left(\phi(x_n) \alpha_{i-s-1} \right) \qquad (i = 1, ..., m), \qquad (6.10)$$

and their derivatives of any order uniformly bounded on \mathbb{R}^n_+ (with respect to ε)

- 3) $c_{i,q}(x^{(n)},t,\varepsilon)$ are polynomials of t;
- 4) v_i is a boundary layer type function of order k_n such that

$$M_0 \overline{v}_i = -\sum_{s=1}^i R_s \overline{v}_{i-s} \qquad (i > 0),$$
 (6.11)

5) the function $w_i + v_i + \varepsilon \alpha_i$ satisfies the boundary conditions of Problem $\mathfrak{D}_{\varepsilon}$.

Before proving Proposition 6.2, we give the following obvious lemma without a proof.

Lemma 6.1. Let Q be a domain in \mathbb{R} , let $p \in \mathbb{N}_0$, $b_i(t) \in \mathbb{C}^p(Q)$ (i = 1, ..., n) and let $A \in \mathbb{R}^{n \times n}$ be a matrix with det $A \neq 0$. Then:

a) the system of equations $A(x_1(t), \ldots, x_n(t))^T = (b_1(t), \ldots, b_n(t))$, has a unique solution, such that $x_r(t) \in \mathbb{C}^p(Q)$ $(r = 1, \ldots, n)$, and

b) *if*

$$\left. \frac{\partial^{s}}{\partial t^{s}} b_{r}\left(t\right) \right|_{t=t_{0}} = 0 \qquad \left(s = 0, ..., p; \ r = 1, ..., n\right),$$

then

$$\frac{\partial^{s}}{\partial t^{s}} x_{r}(t) \Big|_{t=t_{0}} = 0 \qquad (s = 0, ..., p; \ r = 1, ..., n).$$

Proof of Proposition 6.2: Suppose that w_i ($i \leq m$) is a solution of equation (6.10), satisfying boundary conditions (5.8).

We keep the requirement that $w_i + \varepsilon^{k_n} \overline{v}_i$ has to satisfy the conditions (5.9), i.e.

$$\frac{\partial^{k_n+s}\overline{v}_i}{\partial t^{k_n+s}}\bigg|_{t=0} = -\varepsilon^s \frac{\partial^{k_n+s}w_i}{\partial x_n^{k_n+s}}\bigg|_{x_n=0} \qquad (s=0,1,...,l_n-1).$$
(6.12)

where it is assumed that $w_i \equiv 0$ when i > m.

The remainder part of the proof is similar to Proposition 6.1. We prove statements 1) and 2) by induction on i. Obviously, the function w_0 satisfies 1) (see Conditions I and IV, Remark 3.1 and Definition 3.1). Consequently, the function $c_{0,q}(x^{(n)},t)$ also satisfies 1) by Lemma 6.1, and hence the function α_0 satisfies 1) (see representation (6.3)).

By the induction assumption, all coefficients $c_{i-s,q}$ $(0 < s \le i)$ are polynomials of t, all functions \overline{v}_{i-s} $(0 < s \le i)$ are of form (6.8) and the operator $R_{r,s+k_r}$ (s > 0) is independent of D_r (or $\frac{\partial}{\partial t}$, see formula (5.5)). Therefore, the right-hand side of (6.11) is of the form

$$\sum_{s=1}^{l_n} F_s e^{-\lambda_s t},$$

where $F_s = F_s\left(x^{(n)}, t\right)$ is a polynomial of t. Consequently, the solution \overline{v}_i of equation (6.11) has the form

$$\overline{v}_i = \varphi_i + \theta_i,$$

where $\varphi_i = \varphi_i\left(x^{(n)}, t\right)$ is a partial solution of nonhomogeneous equation (6.11), which can be deduced by the uncertain coefficient method (see [17]) and has the form

$$\sum_{s=1}^{l_n} K_s e^{-\lambda_s t}$$

where $K_s = K_s(x^{(n)}, t)$ is a polynomial t order. Its order is higher by 1 than the order of $F_s(x^{(n)}, t)$ of t (see condition (6.1)), and $\theta_i = \theta_i(x^{(n)}, t)$ is a solution of form (6.8) for the corresponding homogeneous equation, satisfying the boundary conditions

$$\left. \frac{\partial^{k_n+s} \theta_i}{\partial t^{k_n+s}} \right|_{t=0} = -\varepsilon^s \frac{\partial^{k_n+s} w_i}{\partial x_n^{k_n+s}} \right|_{x_n=0} - \left. \frac{\partial^{k_n+s} \varphi_i}{\partial t^{k_n+s}} \right|_{t=0} \qquad (s=0,1,...,l_n-1),$$

Consequently, the function v_i is of the form (6.8).

By the induction assumption for $0 \leq j < i$ the functions w_j , α_j and $c_{j,q}$ satisfy 1). Hence, the function h_i (see (6.10)) and its derivatives of any order are uniformly bounded in Ω with respect to ε . Consequently, by Remark 3.2 the function w_i satisfies 1). By Lemma 6.1, it is not difficult to see that the functions $c_{i,q}$ satisfies 1), and hence also α_i satisfies 1).

Statement 3) follows from 1) and 2), and the statement 4) immediately follows by Proposition 6.2 and the definition of the function ϕ .

Proof of theorem 6.1: Let functions w_i (i = 1, ..., m), v_i and α_i $(i = 1, ..., m + k_n)$ satisfy the conditions of Propositions 6.1 and 6.2. Denote

$$u^{(m)} \equiv w_0 + \sum_{i=1}^{m} \varepsilon^i w_i + \sum_{i=0}^{m+k_n} \varepsilon^i \left(v_i + \varepsilon \phi \left(x_n \right) \alpha_i \right).$$

Thus by using forms (4.4) (assuming that N=m) and (5.3) (assuming that $N=m+k_n$) we get

$$L_{\varepsilon}u^{(m)} = \left\{ \left(L_0 + \sum_{s=1}^m \varepsilon^s L^{(s)} + \varepsilon^{N+1} L^{(N+1)} \right) \left(w_0 + \sum_{i=1}^m \varepsilon^i w_i + \sum_{i=0}^{m+k_n} \varepsilon^{i+1} \phi\left(x_n\right) \alpha_i \right) \right\} + \varepsilon^{\gamma} \left\{ \left(M_0 + \sum_{s=1}^{m+k_n} \varepsilon^s R_s + \varepsilon^{m+k_n+1} R_{m+k_n+1} \right) \left(\sum_{i=0}^{m+k_n} \varepsilon^i v_i \right) \right\},$$

Hence

$$L_{\varepsilon}u^{(m)} = L_{0}w_{0} + \left\{ \sum_{i=1}^{m} \varepsilon^{i} \left(L_{0}w_{i} + \sum_{s=1}^{i} L^{(s)}w_{i-s} + \sum_{s=0}^{i} L^{(s)} \left(\phi\left(x_{n}\right)\alpha_{i-s-1}\right) \right) + \sum_{s=0}^{m+1} \varepsilon^{s}L^{(s)} \left(\sum_{i=m+1-s}^{m} \varepsilon^{i}w_{i} + \sum_{i=m-s}^{m+k_{n}} \varepsilon^{i+1}\phi\left(x_{n}\right)\alpha_{i} \right) \right\} +$$

$$+\varepsilon^{\gamma} \left\{ M_0 v_0 + \sum_{i=1}^{m+k_n} \varepsilon^i \left(M_0 v_i + \sum_{s=1}^i R_s v_{i-s} \right) + \sum_{s=1}^{m+k_n+1} \varepsilon^s R_s \sum_{i=m+k_n+1-s}^{m+k_n} \varepsilon^i v_i \right\}.$$

By virtue of (6.10) and (6.11) we get

$$L_{\varepsilon}u^{(m)} = h + \sum_{s=0}^{m+1} \left(\sum_{i=m+1-s}^{m} \varepsilon^{i+s} L^{(s)} w_i + \sum_{i=N-s}^{m+k_n} \varepsilon^{i+1+s} L^{(s)} \left(\phi(x_n) \alpha_i \right) \right) + \sum_{s=1}^{m+k_n+1} \sum_{i=m+k_n+1-s}^{m+k_n} \varepsilon^{i+s} R_s v_i.$$
(6.13)

It is not hard to see that by Propositions 6.1 and 6.2 it follows that there exists M > 0 such that

$$||L^{(N+1-r)}w_i|| \le M \qquad (r = 0, ..., i; i = 0, ..., m),$$

$$||L^{(N+1-r)}(\phi(x_n)\alpha_i)|| \le M \qquad (r = 0, ..., i; i = 0, ..., m + k_n),$$

$$||R_{N+1-r}v_i|| \le M \qquad (r = 0, ..., i; i = 0, ..., m + k_n).$$

Hence from (6.13) that there exists K > 0 such that

$$||L_{\varepsilon}u^{(m)} - h|| \le K\varepsilon^{m+1}.$$

Similar to the proof of Theorem 4.1 we can show that

$$||z_m||_{\varepsilon} = O\left(\varepsilon^{m+1}\right).$$

7 Newton's polyhedron method on \mathbb{R}^n_+ and on a strip

In this Section we will impose the following restriction instead of (A_7) :

 (A'_7) there are natural numbers $p \in [1, l_n], s_1, ..., s_p \ (0 \equiv s_0 < s_1 < ... < s_p \equiv l_n)$ such that for every r = 1, ..., p

a) for r < p (i.e. for p = 1 this condition is absent)

$$\frac{\psi_r - \psi_{r-1}}{s_r - s_{r-1}} < \frac{\psi_{r+1} - \psi_r}{s_{r+1} - s_r},$$

where $\psi_j \equiv \psi\left((k_n + s_j) e^n, (k_n + s_j) e^n\right) (j = 1, ..., p),$ b) for every $\alpha, \beta \in \mathcal{N} + \mathcal{N}$ if $(\alpha_n + \beta_n) \in [2k_n + 2s_{r-1}, 2k_n + 2s_r]$ then

$$\psi(\alpha, \beta) \ge \frac{(\alpha_n + \beta_n - 2k_n)(\psi_r - \psi_{r-1})}{2(s_r - s_{r-1})} \text{ with } \alpha + \beta = (\alpha_n + \beta_n)e^n,$$

$$\psi(\alpha, \beta) > \frac{(\alpha_n + \beta_n - 2k_n)(\psi_r - \psi_{r-1})}{2(s_r - s_{r-1})} \quad \text{with } \alpha + \beta \neq (\alpha_n + \beta_n)e^n.$$

Let $\varkappa_r \in \mathbb{N}_0$ (r = 1, ..., p). For r = 1, ..., p, denote

$$\gamma_r \equiv \max_{\alpha,\beta \in \mathcal{N}} \left(\psi \left(\alpha, \beta \right) - \varkappa_r \left(\alpha_n + \beta_n \right) \right),$$

$$M_{r} \equiv \sum_{\substack{\alpha,\beta \in \mathcal{N} \\ (\alpha_{n}+\beta_{n}) \in [2k_{n}+2s_{r-1},2k_{n}+2s_{r}] \\ \psi(\alpha,\beta)-\varkappa_{r}(\alpha_{n}+\beta_{n})=\gamma_{r}}} D_{y}^{\alpha} \eta_{\alpha,\beta} \left(x^{(n)},0,0\right) D_{y}^{\beta}, \tag{7.1}$$

Proposition 7.1. For M_r (r = 1, ..., p) to be an ordinary differential operator of order $2(k_n + l_n)$ with a minor member of order $2(k_n + s_{r-1})$, it is necessary and sufficient

- 10) $\gamma_r = -\frac{k_n(\psi_r \psi_{r-1})}{s_r s_{r-1}};$ 20) $\varkappa_r = \frac{\psi_r \psi_{r-1}}{2(s_r s_{r-1})}$ is a natural number;
- \mathcal{S}^{0}) the Condition $(A_{7}^{\prime}.b)$ holds.

Proof. Similar to the proof of Proposition 5.1.

Remark 7.1. Note that under Condition (A₆) we can assume that $\varkappa_r = \frac{\psi_r - \psi_{r-1}}{2(s_r - s_{r-1})}$ (r=1,...,p) are natural numbers (otherwise we can obtain this by the change of the variable).

Remark 7.2. Under Conditions (A_1) , (A_6) and (A'_7) (with respect to Remark 7.1) if $\varkappa_r = \frac{\psi_r - \psi_{r-1}}{2(s_r - s_{r-1})}$ (r = 1, ..., p) then the operator M_r is an ordinary differential operator.

Let M_r (r = 1, ..., p) (introduced in (7.1)) be an ordinary differential operator satisfying the conditions of Proposition 7.1. We introduce the following equation (which is the characteristic equation of the operator M_r):

The theorem remains valid with this definition of regular degeneration.

$$\lambda^{2\varkappa_{r}k_{n}}Q_{r}\left(\lambda\right) \equiv \lambda^{2\varkappa_{r}k_{n}} \sum_{\substack{\alpha_{n}e^{n},\beta_{n}e^{n} \in \mathcal{N} \\ (\alpha_{n}+\beta_{n}) \in [2k_{n}+2s_{r-1},2k_{n}+2s_{r}] \\ \psi(\alpha_{n}e^{n},\beta_{n}e^{n}) - \varkappa_{r}(\alpha_{n}+\beta_{n}) = \gamma_{r}}} \eta_{\alpha_{n}e^{n},\beta_{n}e^{n}}\left(x^{(n)},0,0\right) \lambda^{\alpha_{n}+\beta_{n}-2\varkappa_{r}k_{n}} = 0.$$

$$(7.2)$$

Definition 7.1. The degeneration of the Problem $\mathfrak{D}_{\varepsilon}$ into Problem \mathfrak{D}_{0} is called regular if the Conditions (A_1) , (A_6) and (A'_7) hold and if for every r=1,...,p and $(x_1,...,x_{n-1}) \in \mathbb{R}^{n-1}$ the characteristic polynomial $Q_r(\lambda)$ has exactly s_r pairwise different roots with negative real parts.

Theorem 6.1 remains valid with this definition of regular degeneration.

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